

OpenMP

Directive-based Parallel Programming Model for Multi/Many-core Architecture

Akira Nukada

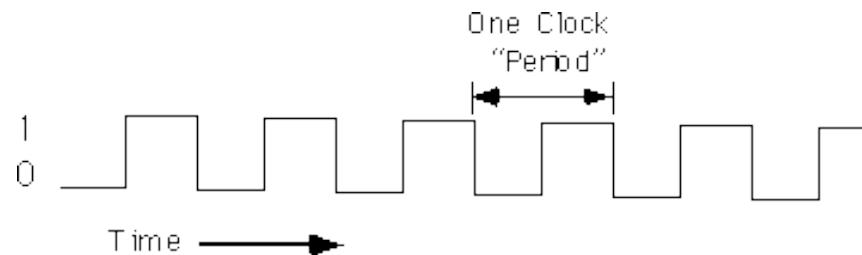
Center for Computational Sciences
University of Tsukuba

Agenda

- ❑ Current processor trends
- ❑ Why we need Multi-threading
- ❑ OpenMP basic
- ❑ Code example
- ❑ Advanced topics
(task parallelism, SIMD, accelerators)

Theoretical Performance

❑ CPU clock



- ❑ CPU Frequency: CPU Clocks per second
- ❑ IPC: Instructions (Operations) Per Clock
- ❑ FLOPS: Floating Operations per Second

$3.0 \text{ GHz} * 1 \text{ IPC} * 1 \text{ core} = 3 \text{ GFLOPS}$

$2.0 \text{ GHz} * 4 \text{ IPC} * 1 \text{ core} = 8 \text{ GFLOPS}$

$1.0 \text{ GHz} * 2 \text{ IPC} * 10 \text{ cores} = 20 \text{ GFLOPS}$

Theoretical Peak Performance



Intel® Xeon® Processor E3-1280 v5
(8M Cache, 3.70 GHz)

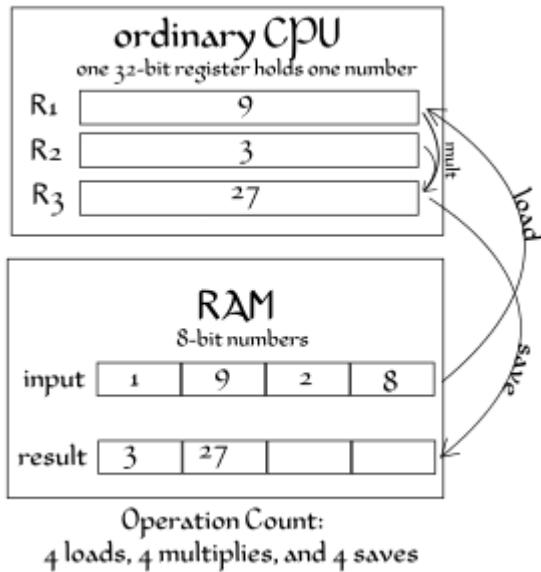
Specifications

Essentials
Performance

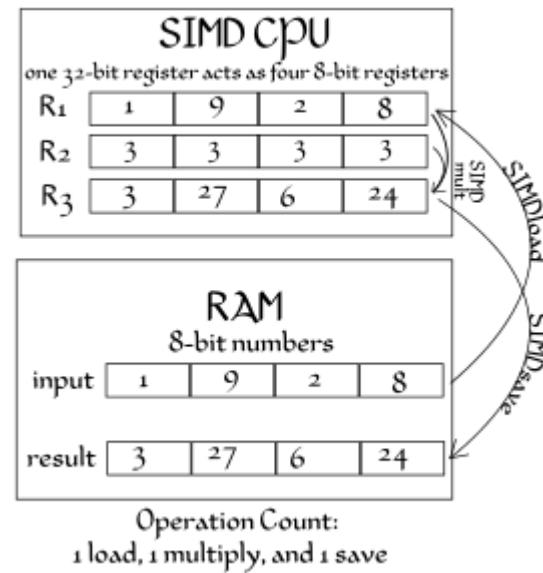
Specifications

- Essentials

Single Core



SIMD/Vector

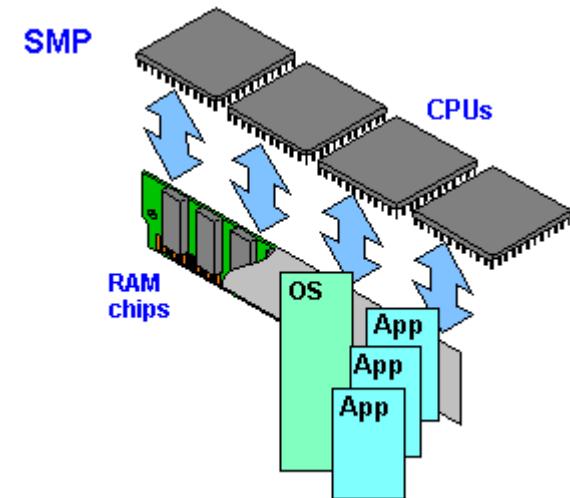


1.0 GHz * 1 IPC
= 1 GFLOPS



SMP

(Shared Memory Parallel)



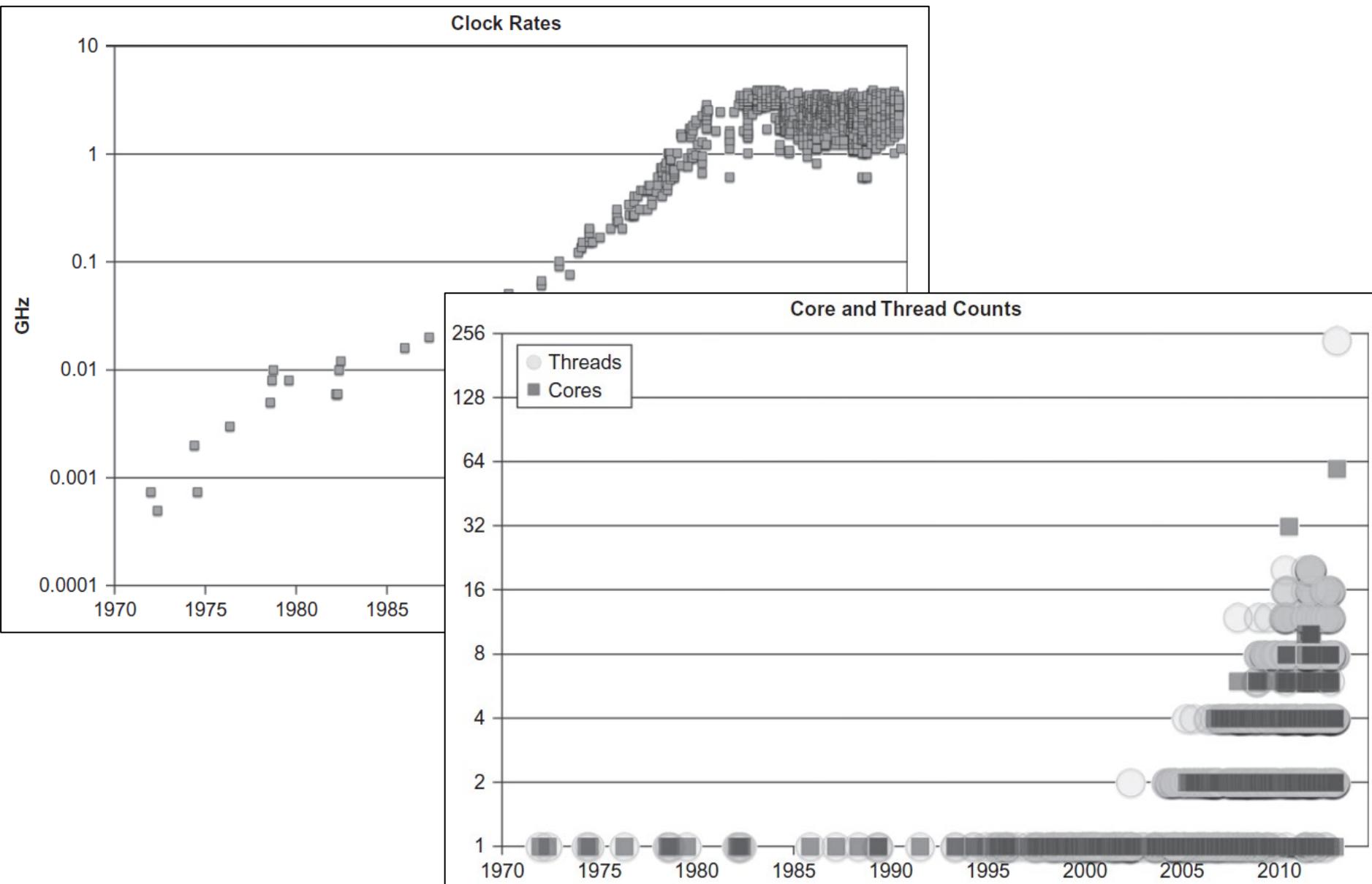
1.0 GHz * 4 IPC
= 4 GFLOPS



1.0 GHz * 4 IPC
* 4 cores = 16 GFLOPS

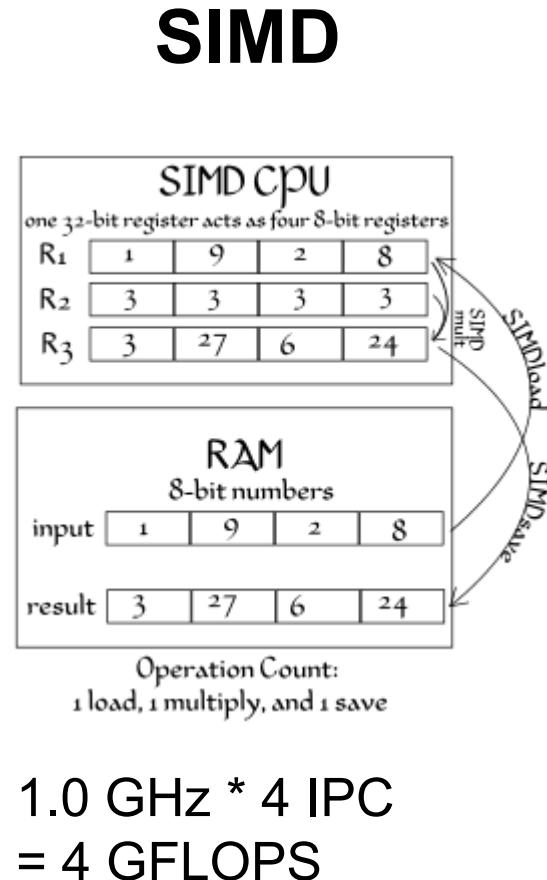


Processor Trends



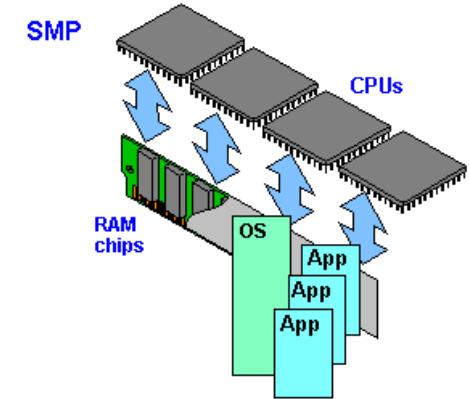
Processor Trends (cont'd)

- ❑ SIMD vector length is getting large
- ❑ Intel Advanced Vector eXtension (AVX)
 - ❑ most Intel processors in the market
 - ❑ 256-bit
 - ❑ 8 32-bit values (int, float)
 - ❑ 4 64-bit values (long, double)
- ❑ Intel AVX-512
 - ❑ Knights Landing Architecture
 - ❑ 512-bit
 - ❑ 16 32-bit values
 - ❑ 8 64-bit values
- ❑ ARM Scalable Vector Extension (SVE)
 - ❑ vector length is not fixed
 - ❑ larger than 512-bit



Why Parallel Programming?

- ❑ clock frequency won't increase, we will get more cores, larger SIMD instructions
- ❑ normal programs use a single core (and SIMD instructions)
- ❑ "Free Lunch is over"



Single core

$$\begin{aligned} 0.5 \text{ GHz} * 1 \text{ SIMD} * 1 \text{ cores} \\ = 0.5 \text{ GFLOPS} \end{aligned}$$

$$\begin{aligned} 2.0 \text{ GHz} * 1 \text{ SIMD} * 1 \text{ cores} \\ = 2 \text{ GFLOPS} \end{aligned}$$

$$\begin{aligned} 4.0 \text{ GHz} * 4 \text{ SIMD} * 1 \text{ cores} \\ = 16 \text{ GFLOPS} \end{aligned}$$

Multi-core

$$\begin{aligned} 3.0 \text{ GHz} * 1 \text{ SIMD} * 1 \text{ cores} \\ = 3 \text{ GFLOPS} \end{aligned}$$

$$\begin{aligned} 3.0 \text{ GHz} * 16 \text{ SIMD} * 1 \text{ cores} \\ = 48 \text{ GFLOPS} \end{aligned}$$

$$\begin{aligned} 3.0 \text{ GHz} * 16 \text{ SIMD} * 16 \text{ cores} \\ = 768 \text{ GFLOPS} \end{aligned}$$

Parallel Programming Models

- There are numerous parallel programming models
- The ones most well-known are:

- Distributed Memory

- ✓ Sockets (standardized, low level)

- ✓ PVM - Parallel Virtual Machine (obsolete)

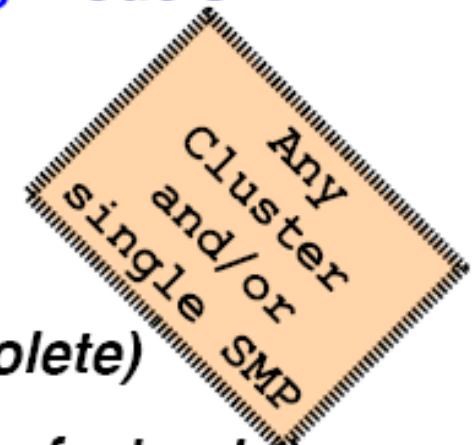
- ✓ MPI - Message Passing Interface (de-facto std)

- Shared Memory

- ✓ Posix Threads (standardized, low level)

- ✓ OpenMP (de-facto standard)

- ✓ Automatic Parallelization (compiler does it for you)



What is OpenMP?

- Programming model and API for shared memory parallel programming
 - It is not a brand-new language.
 - Base-languages(Fortran/C/C++) are extended for parallel programming by directives.
 - Main target area is scientific application.
 - Getting popular as a programming model for shared memory processor s as multi-processor and multi-core processor appears.
- OpenMP Architecture Review Board (ARB) decides spec.
 - Initial members were from ISV compiler vendors in US.
 - Oct. 1997 Fortran ver.1.0 API
 - Oct. 1998 C/C++ ver.1.0 API
 - Latest version, OpenMP 5.1
- <http://www.openmp.org/>



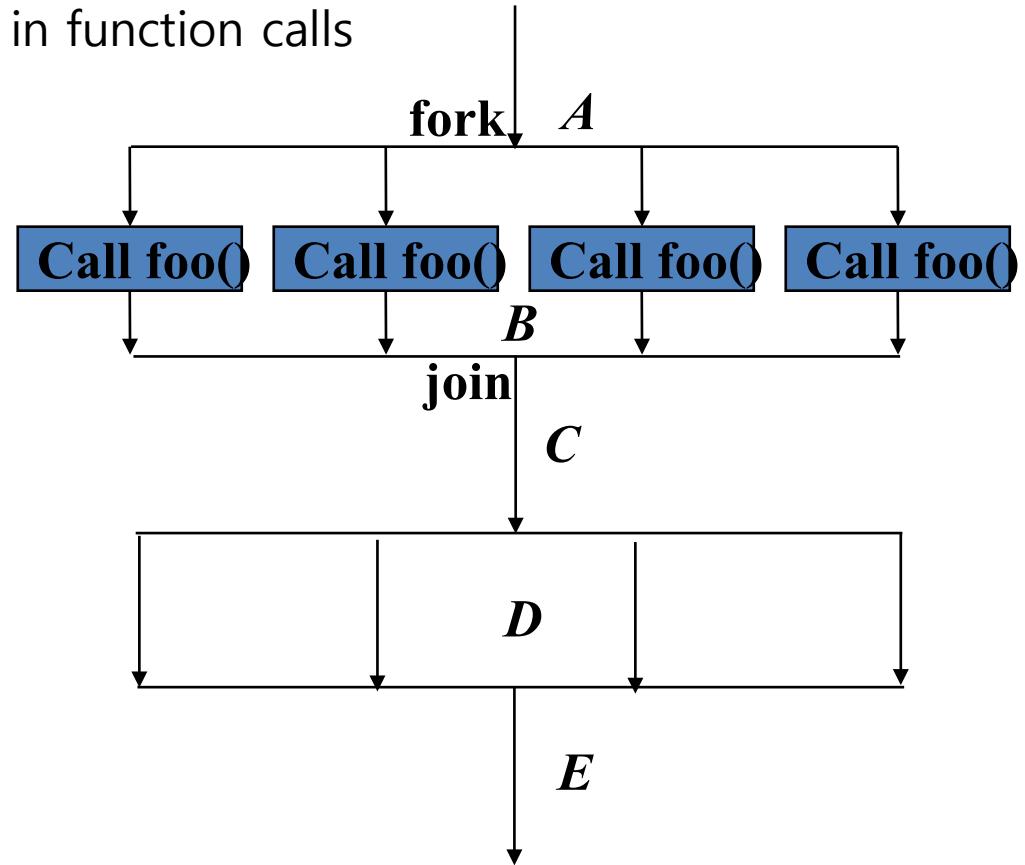
OpenMP API

- It is not a new language!
 - Base languages are extended by compiler directives/pragma, runtime library, environment variable.
 - Base languages: Fortran 90, C, C++
 - Fortran: directive line starting with !\$OMP
 - C: directive by #pragma omp
- Different from automatic parallelization
 - OpenMP parallel execution model is defined explicitly by a programmer.
- If directives are ignored (removed), the OpenMP program can be executed as a sequential program
 - Can be parallelized incrementally
 - Practical approach with respect to program development and debugging.
 - Can be maintained as a same source program for both sequential and parallel version.

OpenMP Execution Model

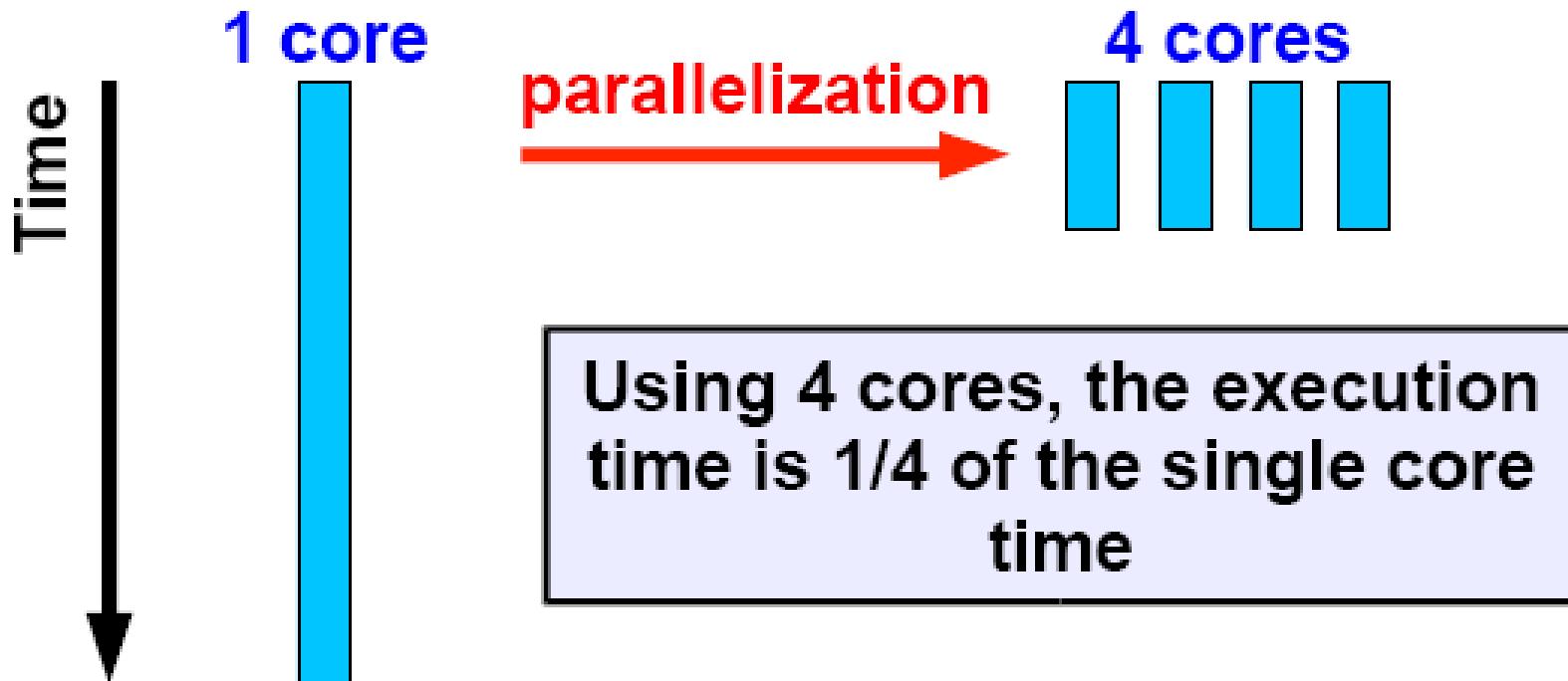
- Start from sequential execution
- Fork-join Model
- parallel region
 - Duplicated execution even in function calls

```
...A...
#pragma omp parallel
{
    foo(); /* ..B... */
}
...C....
#pragma omp parallel
{
    ...D...
}
...E...
```

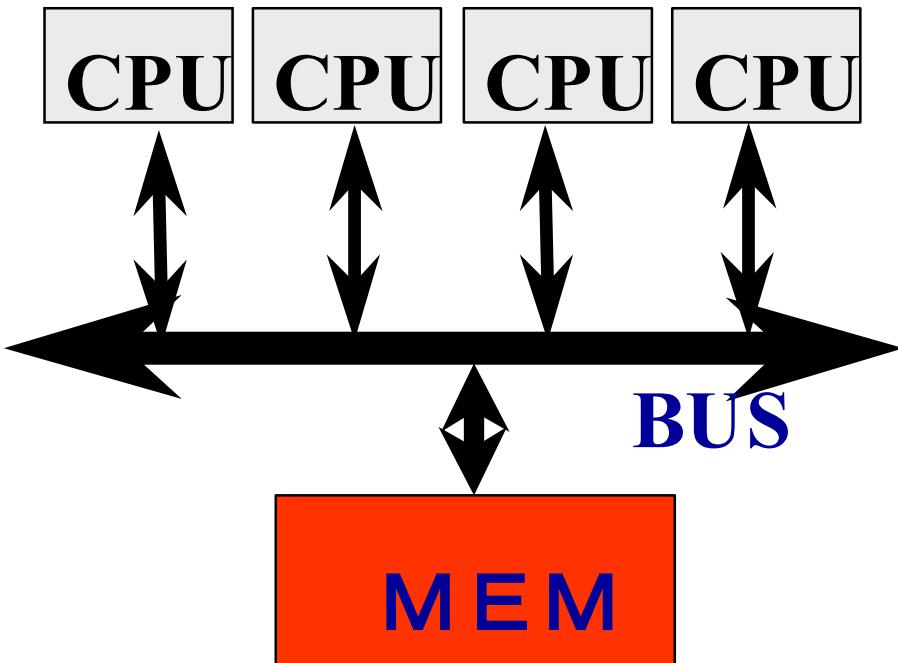


Parallelism Improves Performance

4 times speedup by using 4 cores!



Shared-memory Multicore Processor

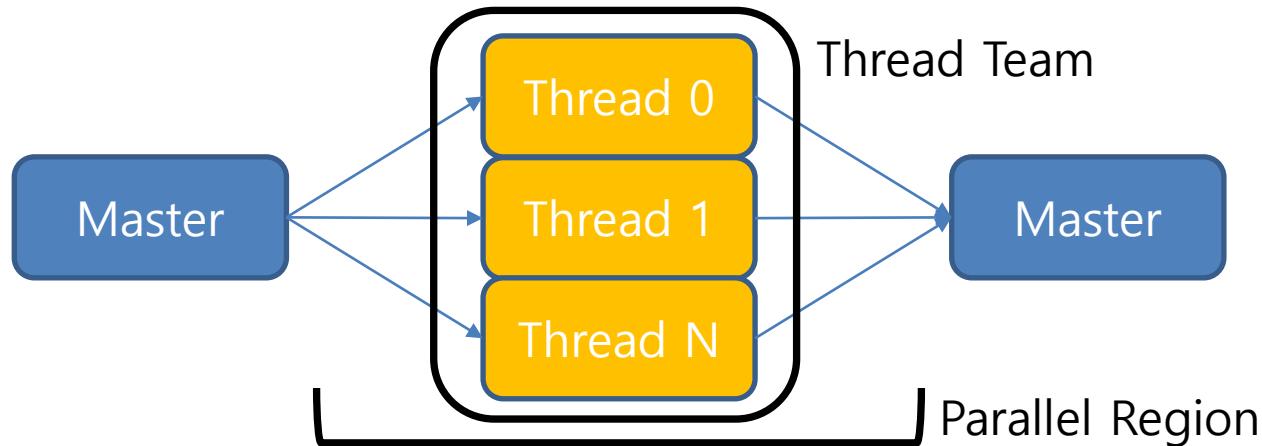


- ◆ Multiple cores share main memory
- ◆ Threads executed in each core(CPU) communicate with each other by accessing shared data in main memory.

parallel Directive

- starts parallel execution
- creates a **thread team**
- by default, all variables are shared among threads

```
int x = 100;  
#pragma omp parallel  
{  
    int my_thread_id = omp_get_thread_num();  
    printf("[%d] x is %d\n", my_thread_id, x);  
    if (my_thread_id == 0) x = 0;  
}  
printf("x is %d\n", x);
```



Compiling OpenMP Code

```
#include <stdio.h>
#include <omp.h>

int main(void) {
    int x = 100;
#pragma omp parallel
{
    int my_thread_id = omp_get_thread_num();
    printf("[%d] x is %d\n", my_thread_id, x);
    if (my_thread_id == 0) x = 0;
}
    printf("x is %d\n", x);
    return 0;
}
```

```
$ gcc -O3 -fopenmp test.c -o test
$ icc -O3 -qopenmp test.c -o test
$ clang -O3 -fopenmp -I$(HEADER) -L$(LIB) -lomp test.c -o test
```

※ LLVM Clang provides the OpenMP library as an external module

Running OpenMP Code

```
$ gcc -O3 -fopenmp test.c -o test
$ export OMP_NUM_THREADS=1
$ ./test
[0] x is 100
x is 0
$ export OMP_NUM_THREADS=4
$ ./test
[0] x is 100
[2] x is 0
[3] x is 0
[1] x is 0
x is 0
$ ./test
[0] x is 100
[2] x is 0
[3] x is 100
[1] x is 100
x is 0
```

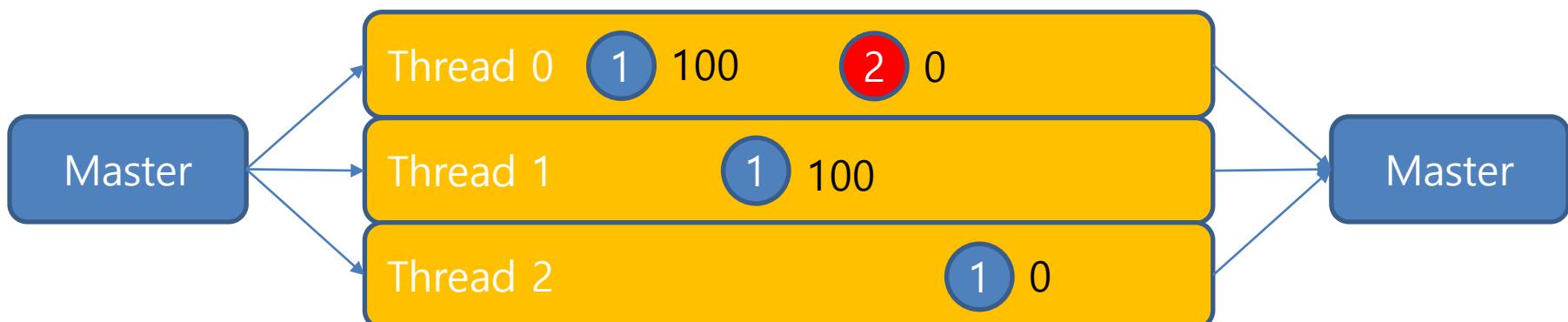
```
int x = 100;
#pragma omp parallel
{
    int my_thread_id = omp_get_thread_num();
    printf("[%d] x is %d\n", my_thread_id, x);
    if (my_thread_id == 0) x = 0;
}
printf("x is %d\n", x);
```

Data Race in Parallel Execution

- all threads do their workloads concurrently
- it can cause some unexpected results

```
int x = 100;  
#pragma omp parallel  
{  
    int my_thread_id = omp_get_thread_num();  
    printf("[%d] x is %d\n", my_thread_id, x);  
    if (my_thread_id == 0) x = 0;  
}  
printf("x is %d\n", x);
```

```
$ ./test  
[0] x is 100  
[1] x is 100  
[2] x is 0  
x is 0
```

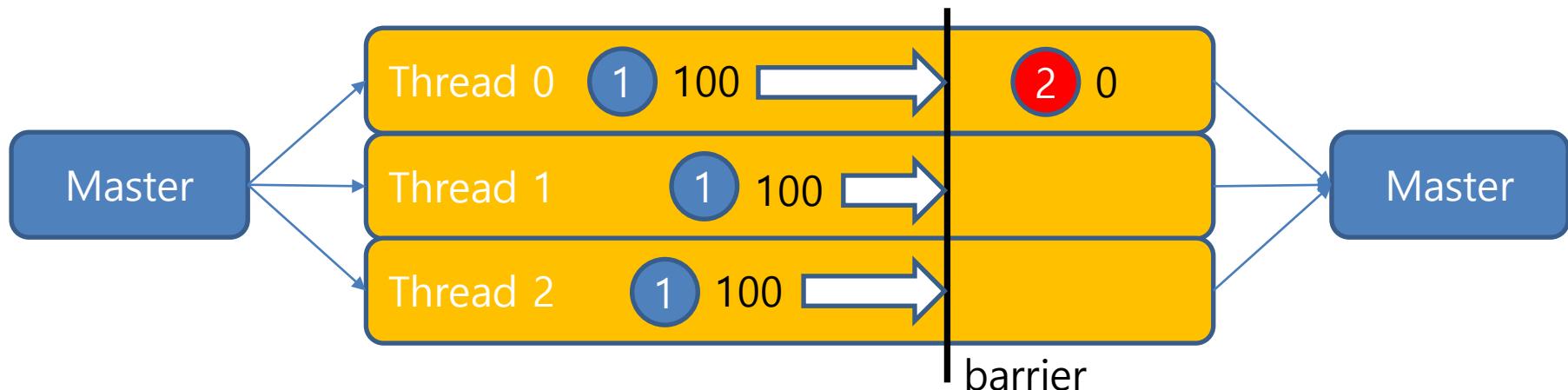


barrier Directive

- ❑ thread stops when they reach a barrier
- ❑ waits until all thread reach the barrier

```
int x = 100;  
#pragma omp parallel  
{  
    int my_thread_id = omp_get_thread_num();  
    printf("[%d] x is %d\n", my_thread_id, x); → 1  
    #pragma omp barrier  
    if (my_thread_id == 0) x = 0; → 2  
}  
printf("x is %d\n", x);
```

```
$ ./test  
[0] x is 100  
[2] x is 100  
[1] x is 100  
x is 0
```

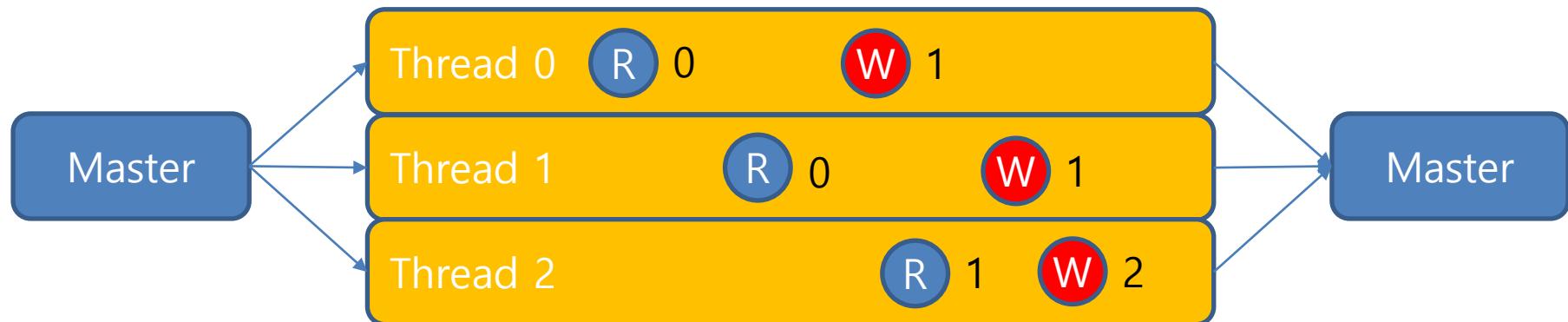


Another Data Race Problem

- ❑ be careful when writing shares variables
- ❑ because mostly statements are not **atomic**
 - ❑ each statement is divided into several instructions

```
int sum = 0;  
#pragma omp parallel  
{  
    sum++; // sum = sum + 1  
}  
printf("sum is %d\n", sum);
```

```
$ export OMP_NUM_THREADS=128  
$ ./test  
sum is 121  
$ ./test  
sum is 120
```

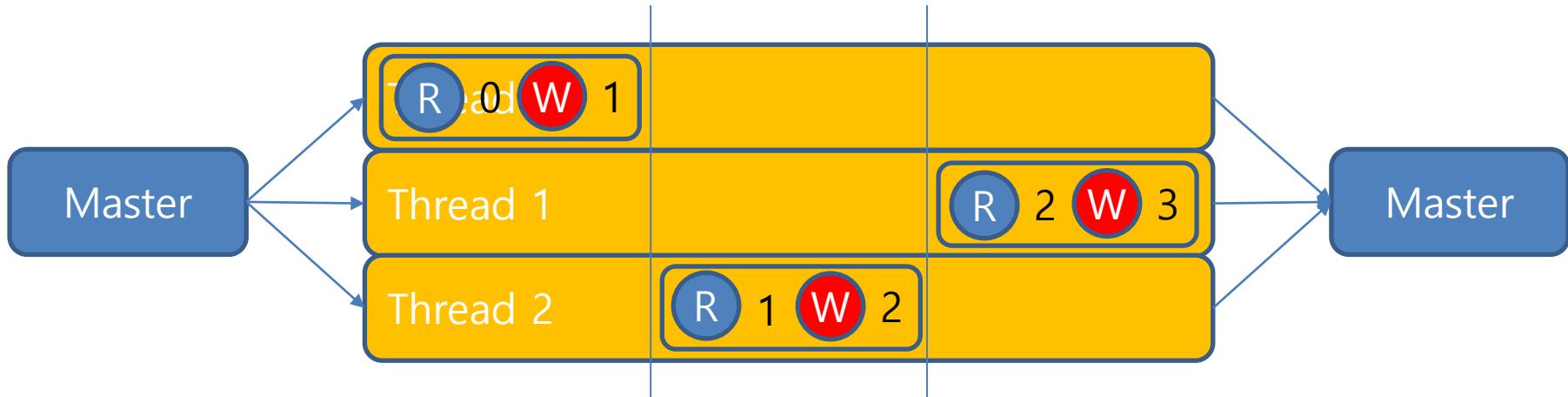


critical Directive

- make target structured block a **critical section**
- executed by a single thread at a time

```
int sum = 0;  
#pragma omp parallel  
{  
#pragma omp critical  
{  
    sum++;  
}  
}  
printf("sum is %d\n", sum);
```

```
$ OMP_NUM_THREADS=128  
$ ./test  
sum is 128  
$ ./test  
sum is 128
```



Data Attribute Clauses

- by default, all variables are shared among threads
- some clauses create thread private variables

```
int x = 100;
int t_private, t_shared;
#pragma omp parallel private(t_private) firstprivate(x)
{
    int my_thread_id = omp_get_thread_num();
    t_private = my_thread_id;
    t_shared = my_thread_id;
#pragma omp barrier
    printf("[%d] private: %d | shared: %d | x: %d\n",
           my_thread_id, t_private, t_shared, x);
}
```

```
$ ./test
[0] private: 0 | shared: 1 | x: 100
[3] private: 3 | shared: 1 | x: 100
[2] private: 2 | shared: 1 | x: 100
[1] private: 1 | shared: 1 | x: 100
```

reduction Clause

- ❑ specified operation at the end of the parallel region
- ❑ op: +, *, -, &, |, ^, &&, ||, max, min
- ❑ reduction variables are private in the parallel region

```
int value = 0;  
#pragma omp parallel reduction(+:value)  
{  
    value = value + omp_get_thread_num();  
}  
printf("value is %d\n", value);
```

```
$ ./test  
value is 6
```

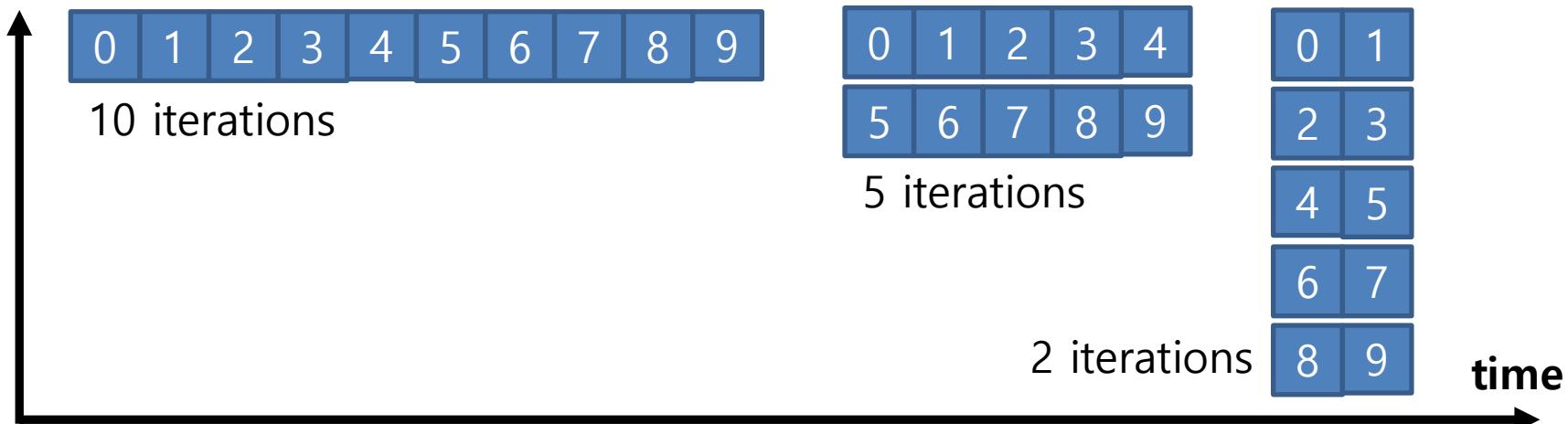


Data Parallelism

- ❑ typical in computational science
- ❑ array references in a loop statement
- ❑ if each iteration can be executed independently, it can be **parallelized**

```
double A[10];
double B[10];
double C[10];
for (int i = 0; i < 10; i++) {
    C[i] = A[i] + B[i];
}
```

number of chunks



loop Directive

- targeting loop statement
 - **for** in C, **do** in Fortran
- work sharing in the current thread team
 - distribute iterations among threads
 - should be specified in a parallel region

```
double A[10];
double B[10];
double C[10];
#pragma omp parallel
{
#pragma omp for
    for (int i = 0; i < 10; i++) {
        C[i] = A[i] + B[i];
    }
}
```

```
#pragma omp parallel for
    for (int i = 0; i < 10; i++) {
        C[i] = A[i] + B[i];
    }
```

Clauses in loop Directive

- data attribute clauses
 - **private, firstprivate, lastprivate**
 - if a variable is accessed frequently, it should be a privatized
- **reduction** clause

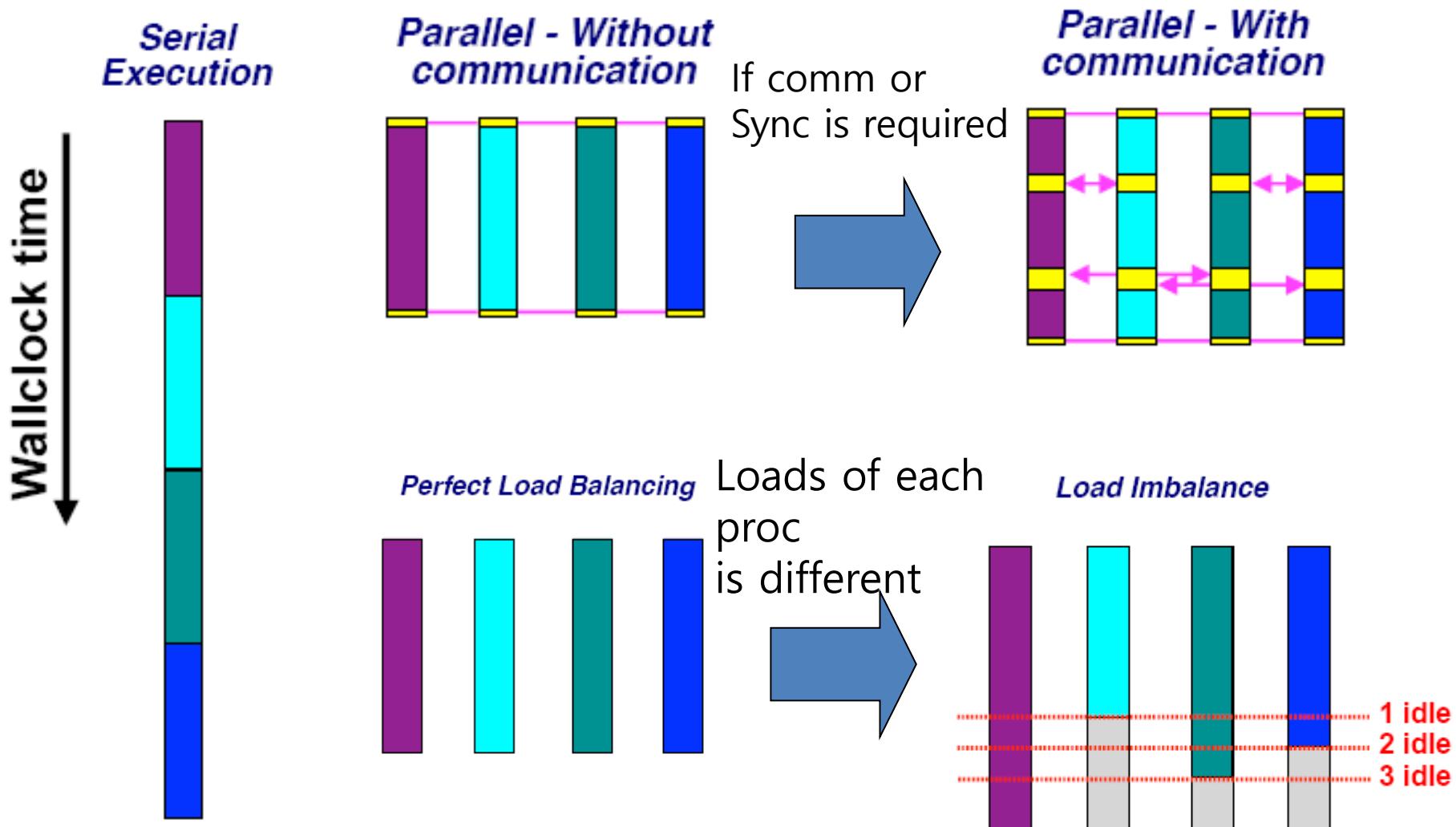
```
double A[N];
double c = INIT_VALUE;
double sum = 0.0;
int iter;
#pragma omp parallel for firstprivate(c) reduction(+:sum) lastprivate(iter)
for (int i = 0; i < N; i++) {
    sum += (A[i] * c);
    iter = i;
}
// iter will be N-1 here
```

1+2+3+4+5+6+7+8+9+10

1+2+3+4+5
6+7+8+9+10

+ reduction

Overhead of Parallel Execution



Implicit Barrier

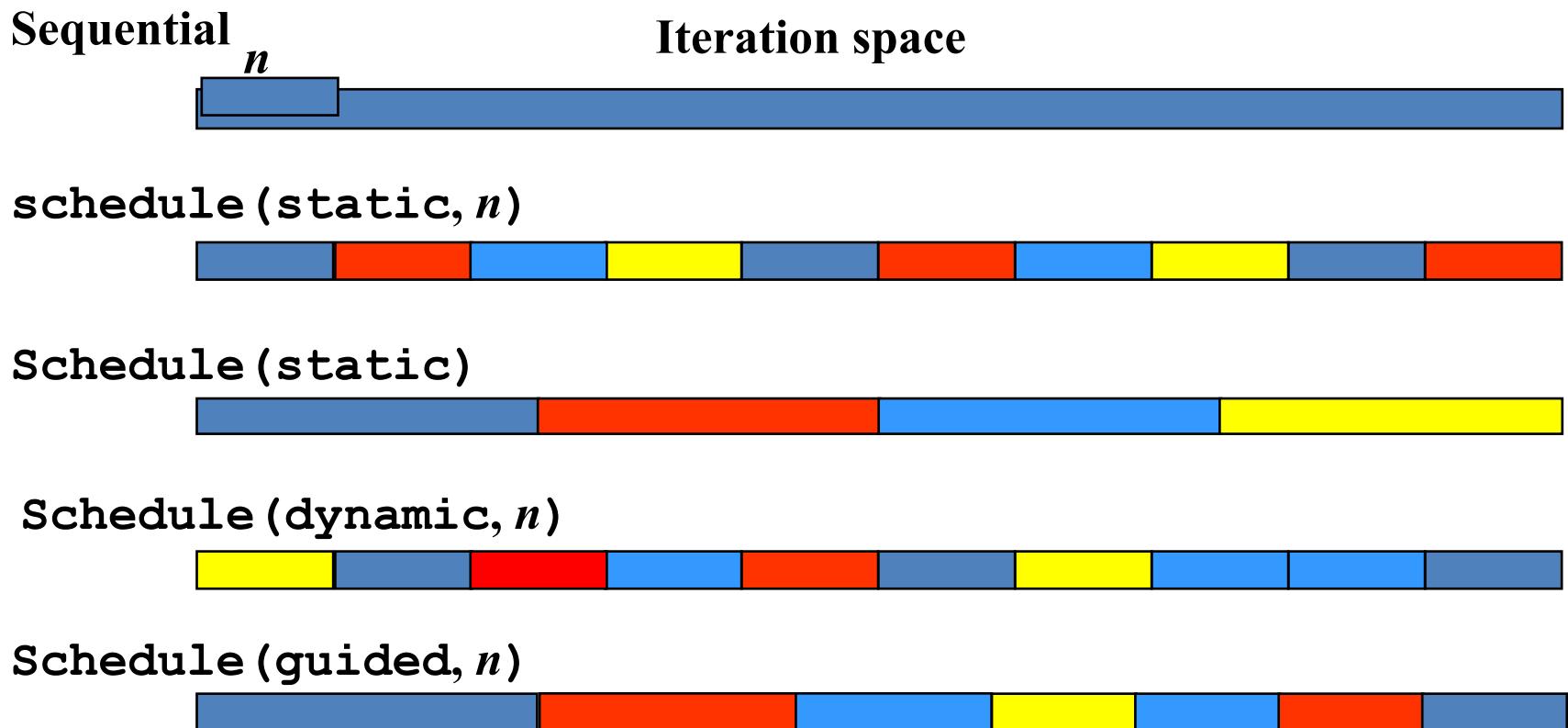
- implicit barrier at the end of **loop** directive
- **nowait** clause removes the implicit barrier
- barrier is needed when data dependency exists

```
#pragma omp parallel
{
# pragma omp for
    for (int i = 0; i < N; i++) {
        C[i] = A[i] + B[i];
    }
# pragma omp for
    for (int i = 0; i < N; i++) {
        E[i] = C[i] + D[i];
    }
}
```

```
#pragma omp parallel
{
# pragma omp for nowait
    for (int i = 0; i < N; i++) {
        C[i] = A[i] + B[i];
    }
# pragma omp for
    for (int i = 0; i < N; i++) {
        F[i] = D[i] + E[i];
    }
}
```

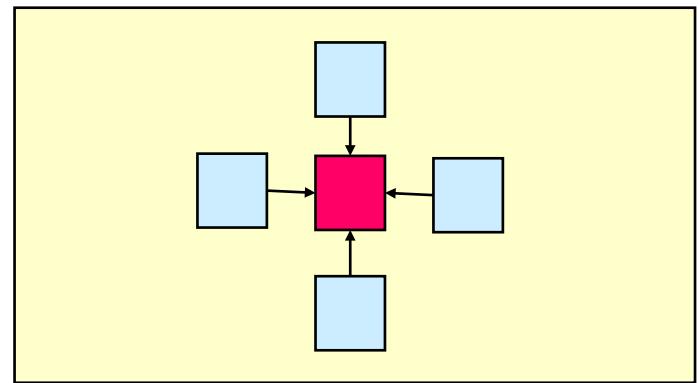
schedule Clause

- ❑ usually **static** shows good performance
- ❑ **dynamic** can be used to reduce load imbalance



Code Example: Laplace Solver

- Explicit solver of Laplace equation
 - Stencil operation: update value with 4-points of up/down/left/right.
 - Use array of “old” and “new”. Compute new by old and replace old with new.
 - Typical parallelization by domain decomposition
 - At each iteration, compute residual
- OpenMP version
 - Parallelize 3 loops
 - OpenMP support only loop parallelization of outer loop.
 - For loop directive is orphan, in dynamic extent of parallel directive.



```

void lap_solve()
{
    int x,y,k;
    double sum;

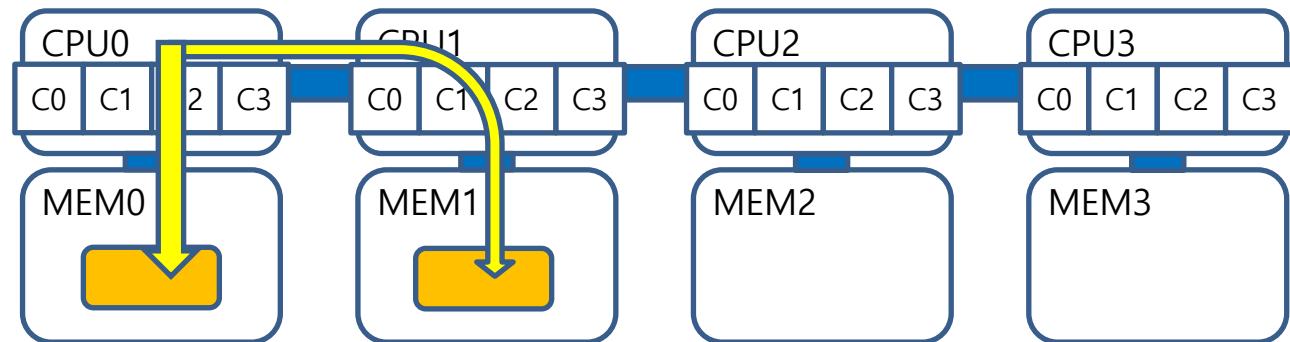
#pragma omp parallel private(k,x,y)
{
    for(k = 0; k < NITER; k++) {
        /* old <- new */
#pragma omp for
        for(x = 1; x <= XSIZE; x++)
            for(y = 1; y <= YSIZE; y++)
                uu[x][y] = u[x][y];
        /* update */
#pragma omp for
        for(x = 1; x <= XSIZE; x++)
            for(y = 1; y <= YSIZE; y++)
                u[x][y] = (uu[x-1][y] + uu[x+1][y] + uu[x][y-1] + uu[x][y+1])/4.0;
    }
}

/* check sum */
sum = 0.0;
#pragma omp parallel for private(y) reduction(+:sum)
for(x = 1; x <= XSIZE; x++)
    for(y = 1; y <= YSIZE; y++)
        sum += (uu[x][y]-u[x][y]);
printf("sum = %g\n",sum);
}

```

NUMA Architecture

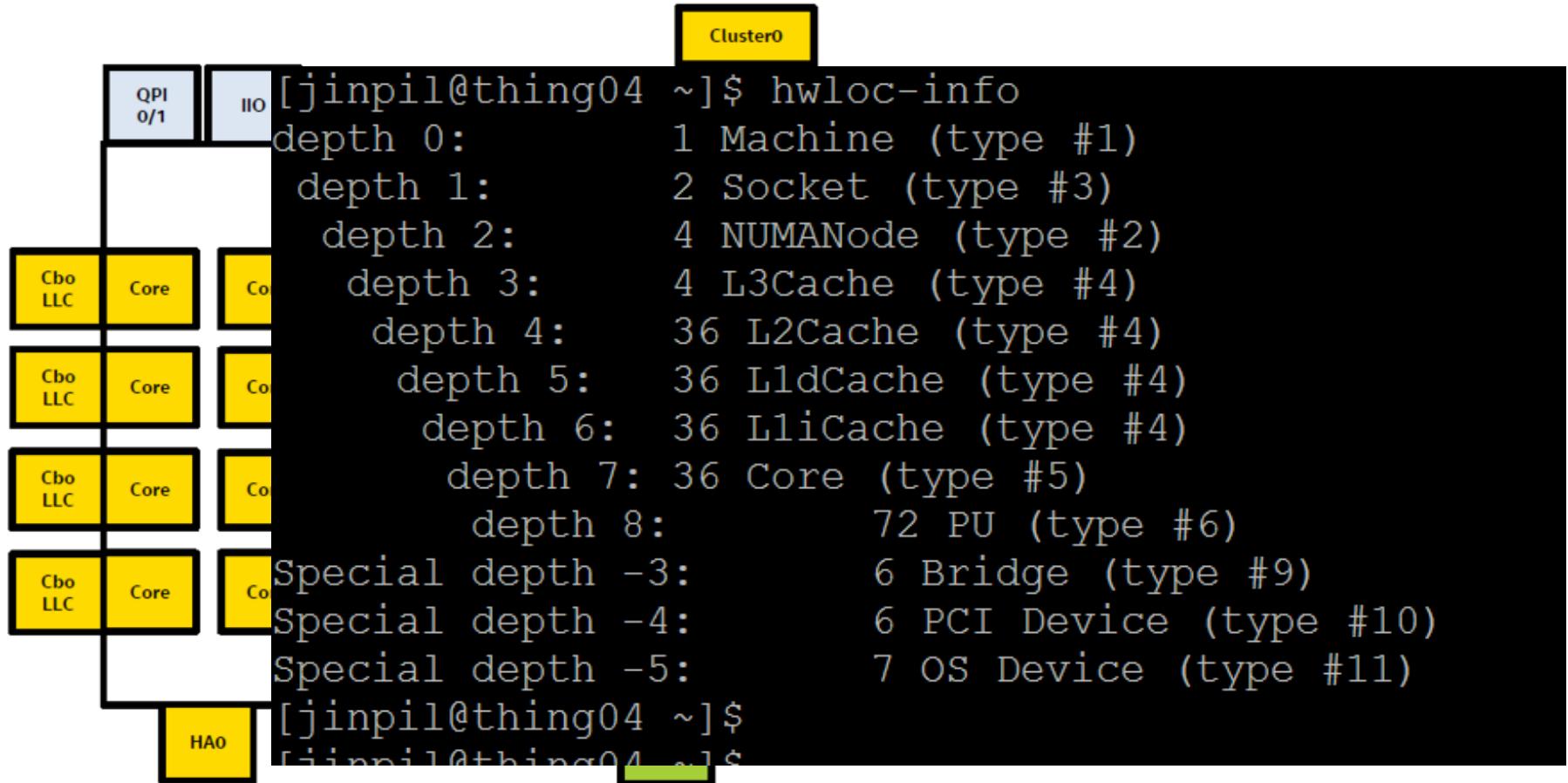
- ❑ Non-Uniform Memory Access (NUMA)
 - ❑ each NUMA node has dedicated memory
 - ❑ can access remote memory
 - ❑ access cost is not uniform
- ❑ current trends
 - ❑ improves performance by increasing NUMA nodes
 - ❑ NUMA nodes in a single processor
- ❑ parallel program should be optimized for NUMA
 - ❑ **data locality** is important on NUMA architecture



NUMA Node in a Processor

- ☐ Cluster-on-Die (COD) Mode in Xeon Processor
- ☐ Knights Landing Architecture has 4 NUMA nodes

COD Mode for 18C E5-2600 v3



NUMA Optimization in OpenMP

- ❑ STREAM Triad: benchmark for memory bandwidth
- ❑ key is how to initialize data
- ❑ *ser init*: no OMP directive in init()
- ❑ *par init*: using OMP directive in init()

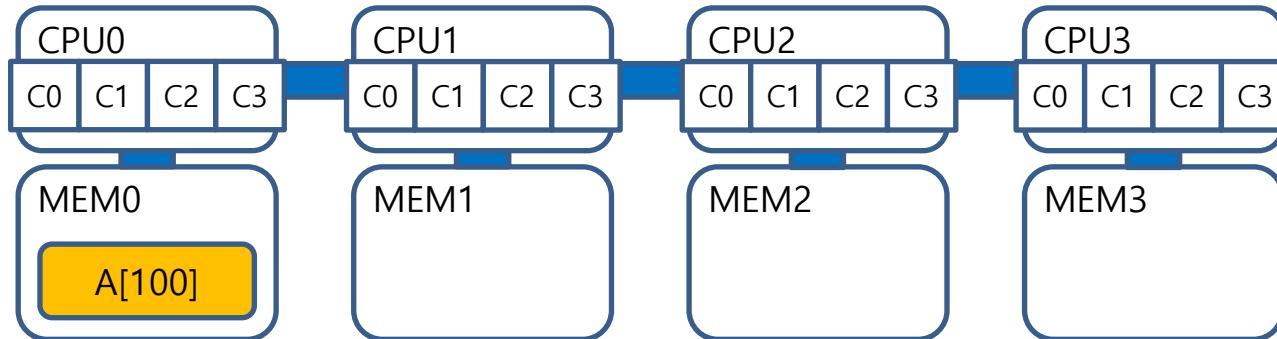
```
void init() {  
#pragma omp parallel for  
    for (int j=0; j<N; j++) {  
        b[j] = create_value_b(j);  
        c[j] = create_value_c(j);  
    }  
}  
  
void STREAM_Triad(double scalar) {  
#pragma omp parallel for  
    for (int j=0; j<N; j++)  
        a[j] = b[j]+scalar*c[j];  
}
```

Linux First-touch Memory Allocation:

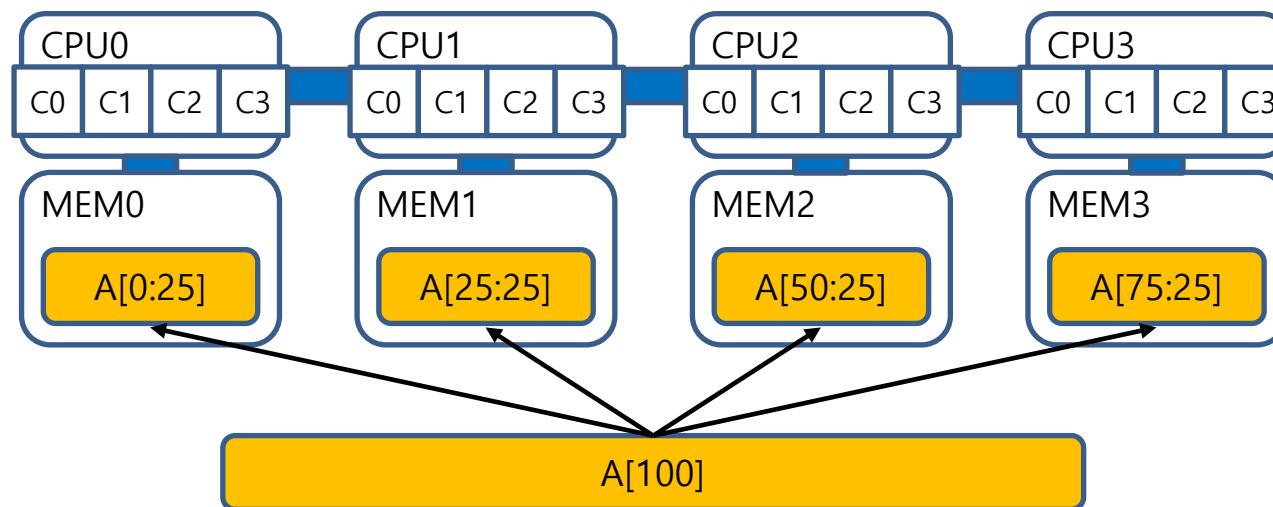
Memory allocation happens at the first touch. The memory region will be allocated close to the accessing CPU.

Data Distribution with First-touch Allocation

- ❑ *ser init*: all data will be allocated on NUMA node 0

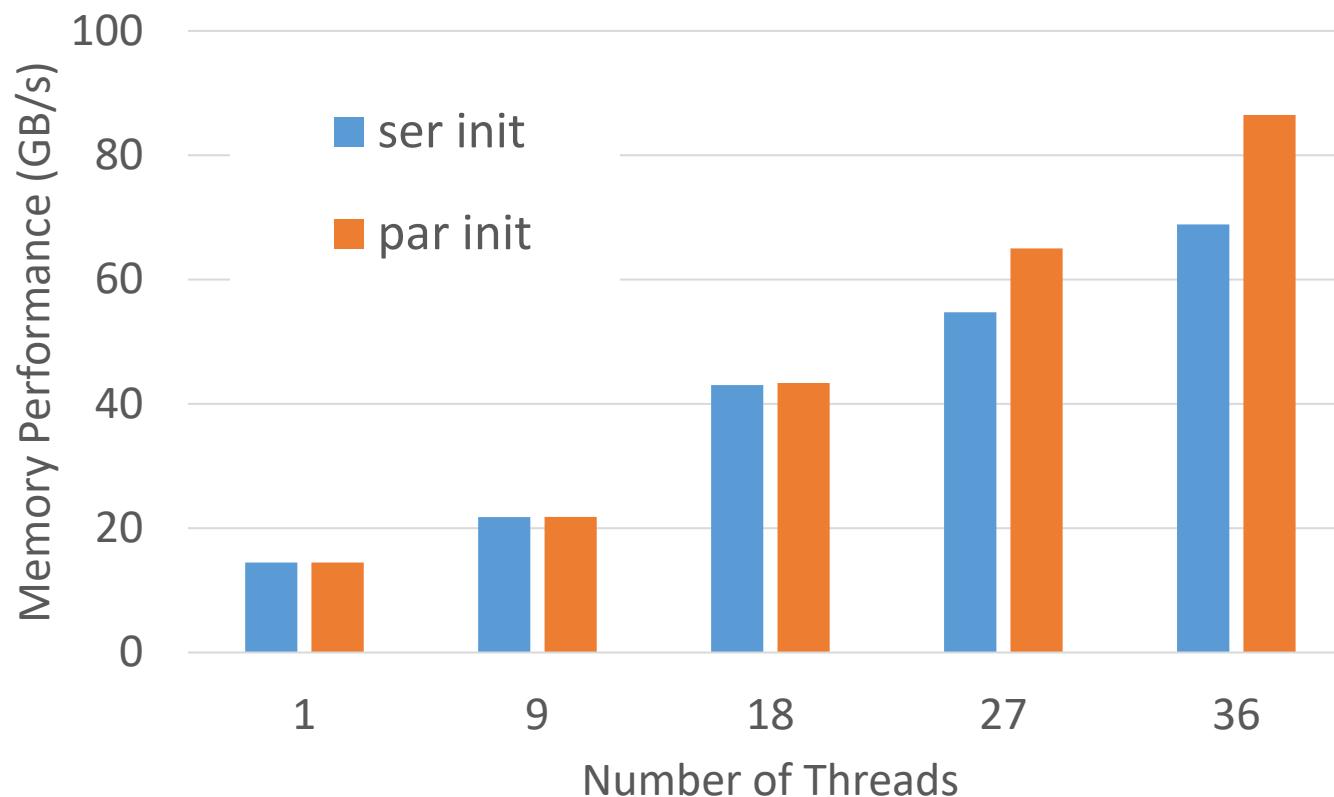


- ❑ *par init*: data will be distributed among NUMA nodes



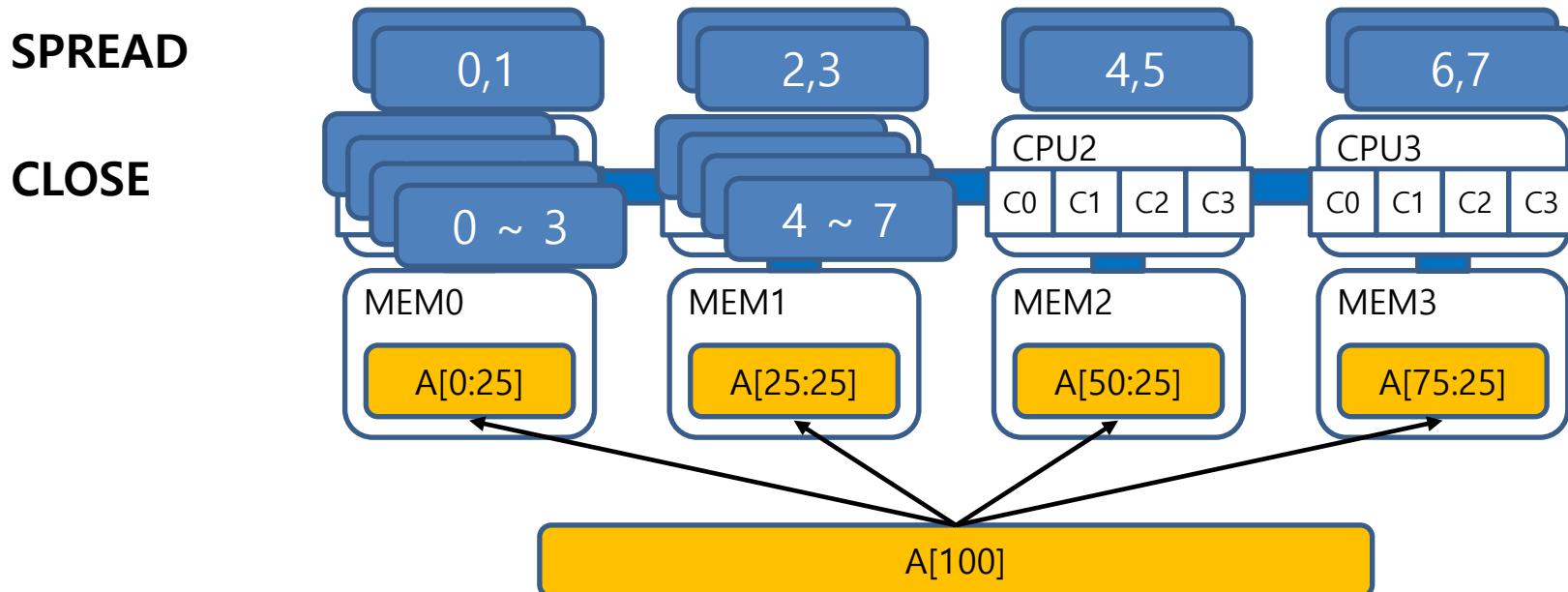
Performance: STREAM Triad

- *ser init*: all data is on NUMA node 0
 - remote memory access on NUMA node 1, 2,
- *par init*: all data is on each local memory
 - no remote memory access



Thread Affinity

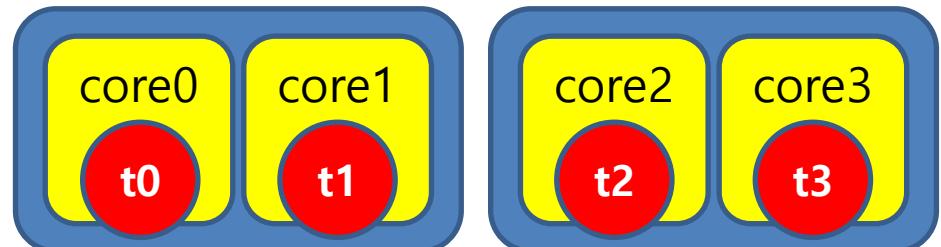
- ❑ OpenMP thread is equal to a physical core
- ❑ how to assign it to a physical core (**thread affinity**) is run time dependent
- ❑ you can control it by using **OMP_BIND_PROC / OMP_PLACES**



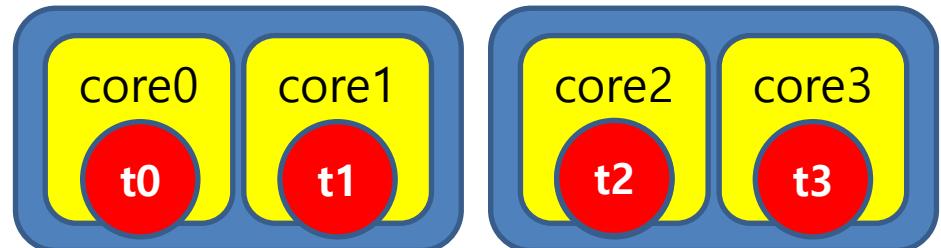
Thread Affinity Option in OpenMP

- ❑ can be specified via environment variables
- ❑ **OMP_PROC_BIND**
 - ❑ CLOSE | SPREAD
 - ❑ **proc_bind** clause available in parallel directive
- ❑ **OMP_PLACES**
 - ❑ THREADS | CORES | SOCKETS

CLOSE

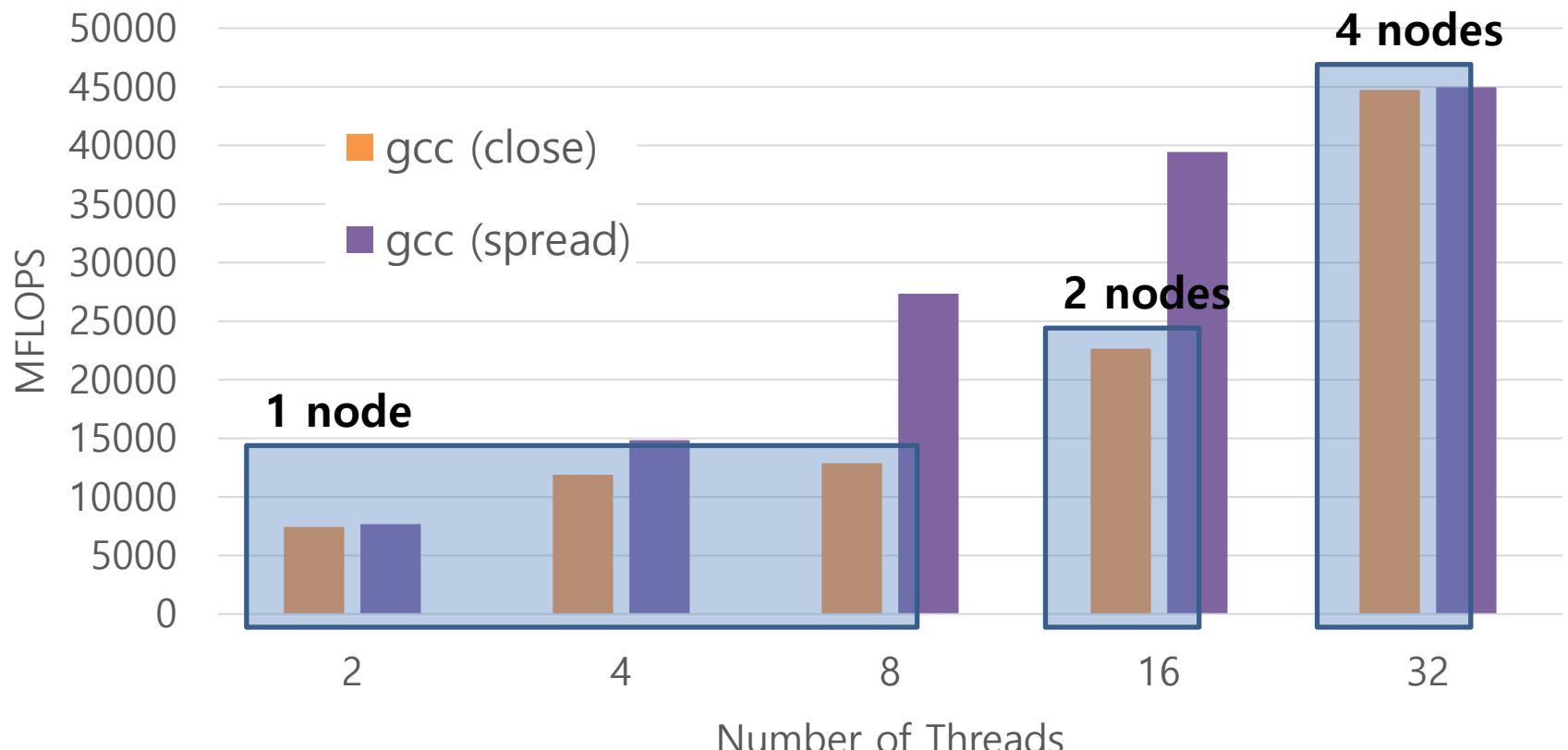


SPREAD



Performance Impact with Thread Affinity

- comparison between CLOSE / SPREAD
- SPREAD uses more NUMA nodes
- Target Platform: 9 cores per NUMA node



NAS Parallel Benchmarks MG Kernel

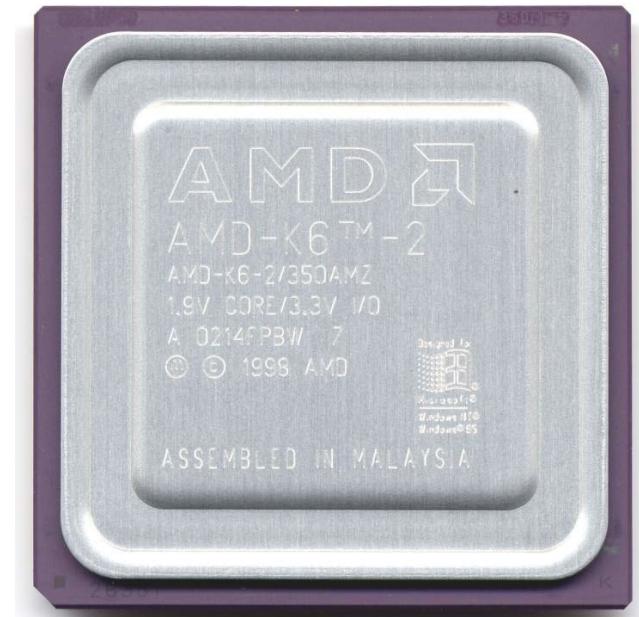
History of SIMD Instructions

□ Intel MMX

- MMX Pentium (233 MHz)
- 57 instructions for **2 32-bit integers (64-bit)**

□ AMD 3DNow!

- AMD K6-2 (300 MHz)
- MMX + 21 instructions for **2 32-bit float values (64-bit)**



SIMD Instructions (cont'd)

❑ Intel SSE

- ❑ 128-bit SIMD
- ❑ supports 32-bit floating point operations

❑ Intel SSE2

- ❑ added 64-bit floating point operations

❑ Intel SSE3

- ❑ added DSP-oriented, complex operations

❑ Intel SSE4

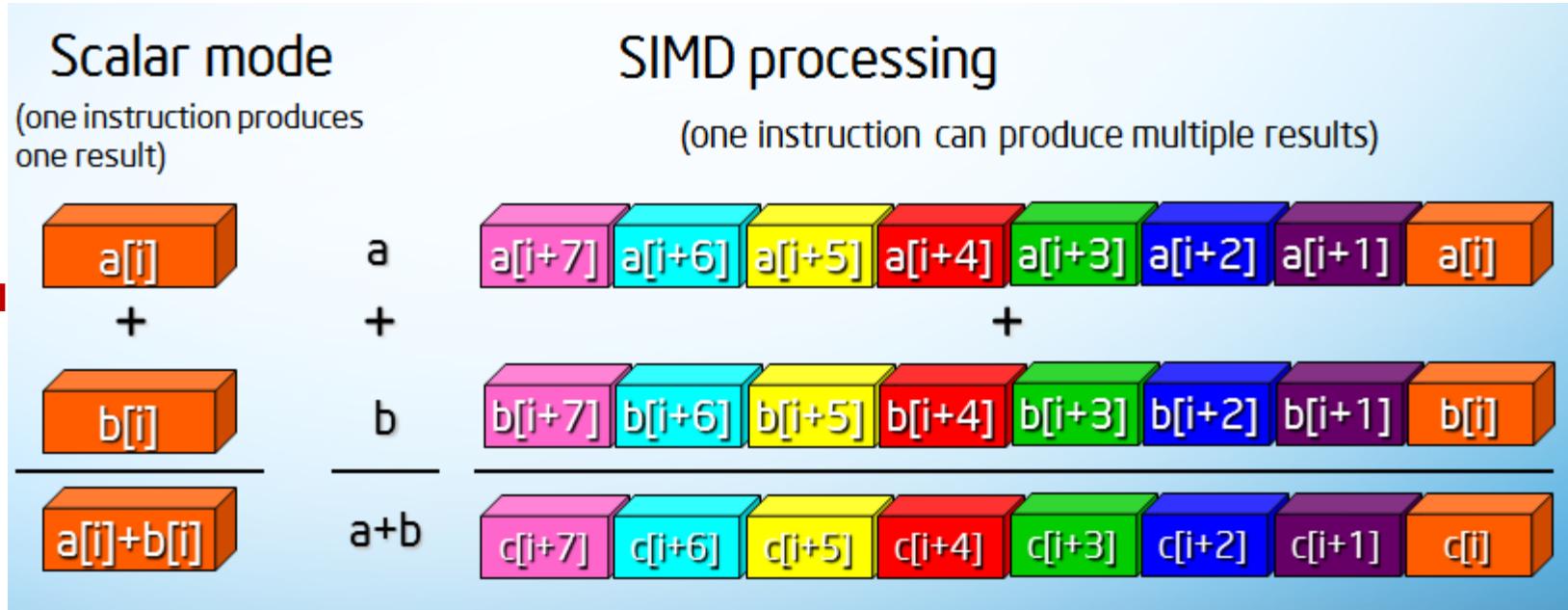
- ❑ added a dot-product instruction, etc...

❑ ARM Advanced SIMD (NEON)

- ❑ DSP-oriented SIMD instruction
- ❑ 64-bit/128-bit SIMD
- ❑ supports 32-bit floating point operations

How SIMD works

- calculate multiple values in one instruction



Intel Developer Zone

SIMD Vectorization

- ❑ calculate multiple values in one instruction
- ❑ most fine-grain level parallelism
- ❑ instruction level parallelism
- ❑ essential to exploit the **core** performance
 - ❑ Intel Xeon Phi 7290 (Knights Landing)
 - ❑ AVX-512, 72 cores
 - ❑ single core (NO SIMD)
 $2 \text{ ALU} \times 2 \text{ OPs} \times 1.5 \text{ GHz} = 6 \text{ GFLOPS}$
 - ❑ single core + **SIMD** (64-bit FP)
8 FPs $\times 2 \text{ ALU} \times 2 \text{ OPs} \times 1.5 \text{ GHz}$
= 48 GFLOPS
 - ❑ **multiple cores** + **SIMD** (64-bit FP)
72 cores $\times 8 \text{ FPs} \times 2 \text{ ALU} \times 2 \text{ OPs} \times 1.5 \text{ GHz}$
= 3,456 GFLOPS

How to Program: Assembly Language

- ❑ most efficient
- ❑ least productive
- ❑ instruction set dependent

```
float A[1000];
float B[1000];
float C[1000];

void foo() {
    for (i = 0; i < 1000; i++) {
        C[i] = A[i] + B[i];
    }
}
```

.L3:

```
movaps A(%rax), %xmm0
addq $16, %rax
addps B-16(%rax), %xmm0
movaps %xmm0, C-16(%rax)
cmpq $4000, %rax
jne .L3
```

How to Program: Intrinsic Function

- ❑ better productivity
- ❑ equivalent performance to assembly languages
- ❑ still difficult to use
- ❑ instruction set dependent

```
float A[1000];
float B[1000];
float C[1000];

void foo() {
    for (i = 0; i < 1000; i++) {
        C[i] = A[i] + B[i];
    }
}
```

```
float A[1000];
float B[1000];
float C[1000];

void foo() {
    for (i = 0; i < 1000; i+=4) {
        __m128 t0, t1;
        t0 = _mm_load_ps(&A[i]);
        t1 = _mm_load_ps(&B[i]);
        t0 = _mm_add_ps(t0, t1);
        _mm_store_ps(&C[i], t0);
    }
}
```

How to Program: Auto Vectorization

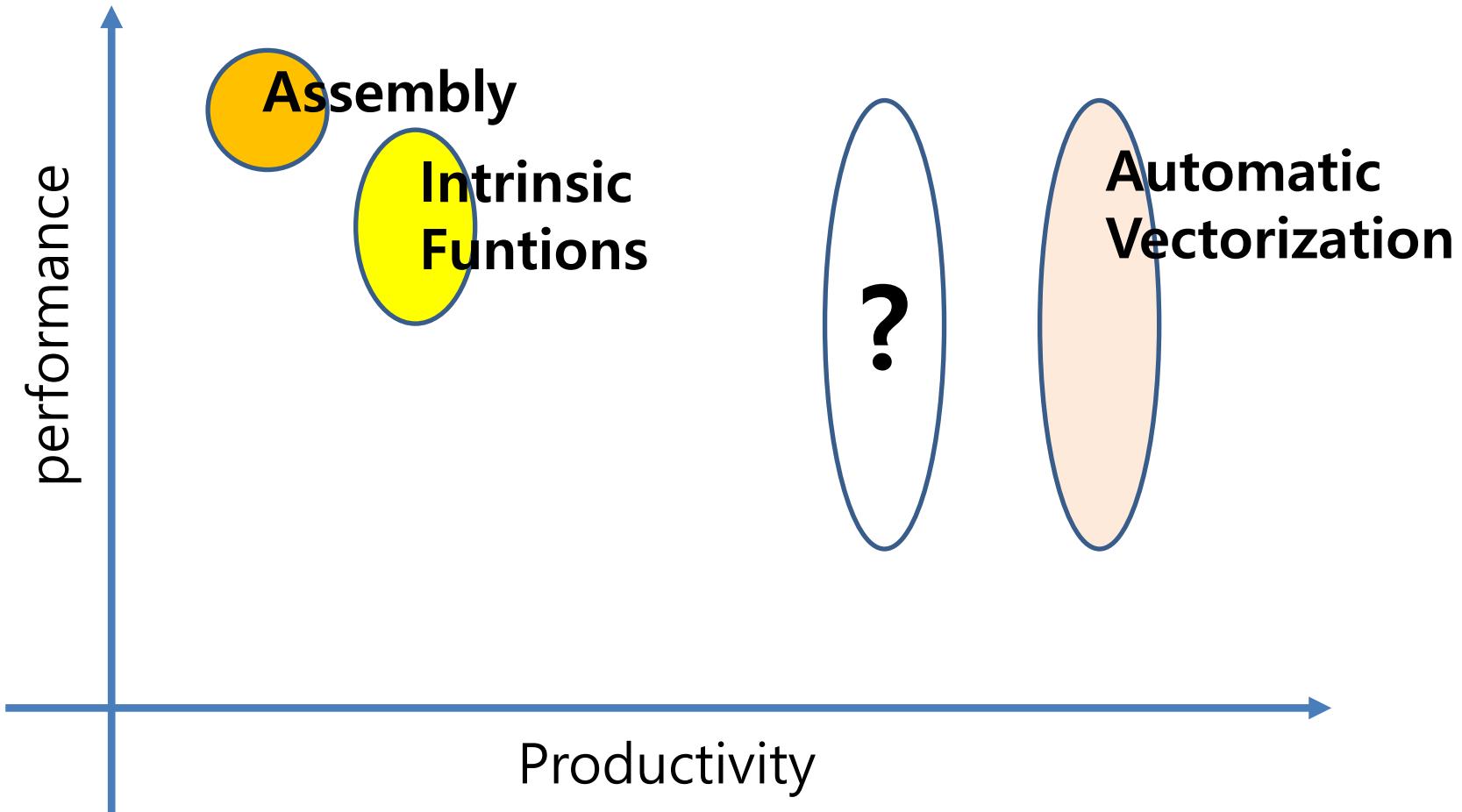
- ❑ program in high-level languages (C, C++, Fortran)
- ❑ compiler generates vector code
- ❑ most productive
- ❑ difficult to optimize

```
float A[1000];
float B[1000];
float C[1000];

void foo() {
    for (i = 0; i < 1000; i++) {
        C[i] = A[i] + B[i];
    }
}
```



Productivity & Performance



How to Program: OpenMP

- ❑ program in high-level languages (C, C++, Fortran)
- ❑ compiler generates vector code ...
- ❑ according to **OpenMP directives**
- ❑ **explicit** SIMD programming in C/C++, Fortran

```
float A[1000];
float B[1000];
float C[1000];

void foo() {
    for (i = 0; i < 1000; i++) {
        C[i] = A[i] + B[i];
    }
}
```

```
float A[1000];
float B[1000];
float C[1000];

void foo() {
    #pragma omp simd
    for (i = 0; i < 1000; i++) {
        C[i] = A[i] + B[i];
    }
}
```

simd Directive

- ❑ explicitly specifying loop vectorization
- ❑ provides hidden information for SIMD vectorization

```
extern double *a;  
extern double *b;  
extern double *c;  
  
for (int i = 0; i < 128; i++) {  
    c[i] += a[i] * b[i];  
}
```

vmovupd a+1024(%rcx), %ymm1
vmulpd b+1024(%rcx), %ymm1, %ymm1
vaddpd c+1024(%rcx), %ymm1, %ymm1
vmovupd %ymm1, c+1024(%rcx)

or it may not be vectorized...

```
extern double *a;  
extern double *b;  
extern double *c;  
  
#pragma omp simd aligned(a,b,c:32)  
for (int i = 0; i < 128; i++) {  
    c[i] += a[i] * b[i];  
}
```

vmovapd (%rcx,%rdi,8), %ymm1
vmulpd (%rdx,%rdi,8), %ymm1, %ymm1
vaddpd (%rsi,%rdi,8), %ymm1, %ymm1
vmovapd %ymm1, (%rsi,%rdi,8)

Clauses in **simd** Directive

- data attribute clauses
 - **private, firstprivate**
- **reduction** clause
- **aligned** clause
- **parallel for simd** → thread parallel + SIMD vectorization

```
extern double *A;
extern double *B;
double sum;
#pragma omp parallel for simd reduction(+:sum) aligned(A,B:32)
for (int i = 0; i < N; i++) {
    sum += (A[i] + B[i]);
}
```

- should make memory allocation aligned by using:
 - `posix_memalign()`, `aligned_alloc()`

declare simd Directive

- ❑ whole function vectorization
- ❑ scalar function → vector function
- ❑ should be used in a SIMD-vectorized loop

```
extern double *a;
extern double *b;
extern double *c;

#pragma omp declare simd notinbranch
double mult(double a, double b) {
    return a * b;
}

#pragma omp simd aligned(a,b,c:32)
for (int i = 0; i < 1024; i++) {
    c[i] = mult(a[i], b[i]);
}
```

Clauses in `declare simd` Directive

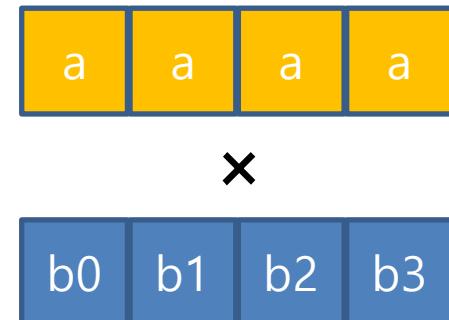
- ❑ **notinbranch** clause
- ❑ **uniform** clause
- ❑ **linear** clause

```
#pragma omp declare simd notinbranch uniform(a)
```

```
double mult(double a, double b) {  
    return a * b;  
}
```

```
extern double a;  
extern double *b;  
extern double *c:
```

```
#pragma omp simd aligned(b,c:32)  
for (int i = 0; i < 1024; i++) {  
    c[i] = mult(a, b[i]);  
}
```



About **simd** Directive

- ❑ multithreading will improve performance instantly
- ❑ using **simd** directive is not straightforward
 - ❑ compiler already vectorized your code
 - ❑ most (simple) sequential code is memory-bound

```
for (int i = 0; i < N; i++) {  
    for (int j = 0; j < N; j++) {  
        for (int k = 0; k < N; k++) {  
            C[i][j] += A[i][k] * B[k][j];  
        }  
    }  
}
```

1 GFLOPS

```
for (int i = 0; i < N; i++) {  
    for (int k = 0; k < N; k++) {  
        for (int j = 0; j < N; j++) {  
            C[i][j] += A[i][k] * B[k][j];  
        }  
    }  
}
```

5.4 GFLOPS

```
for (int ii = b; ii < b+BLK; ii++) {  
    for (int kk = b; kk < b+BLK; kk++) {  
        for (int jj = b; jj < b + BLK; jj++) {  
            C[ii][jj] += A[ii][kk] * B[kk][jj];  
        }  
    }  
}
```

9.4 GFLOPS

still, 25% of
peak performance

Many-core Architecture

- ❑ low-power + many-core
- ❑ power efficient architecture
- ❑ first generation: accelerator



CPU

1~10 cores

General-purpose

Accelerator
Many-core
Power-efficient

Graphics Processing Unit

- ❑ originally for CG, gaming → programmable
- ❑ architecture dedicated to calculation
- ❑ high Watt/Flops

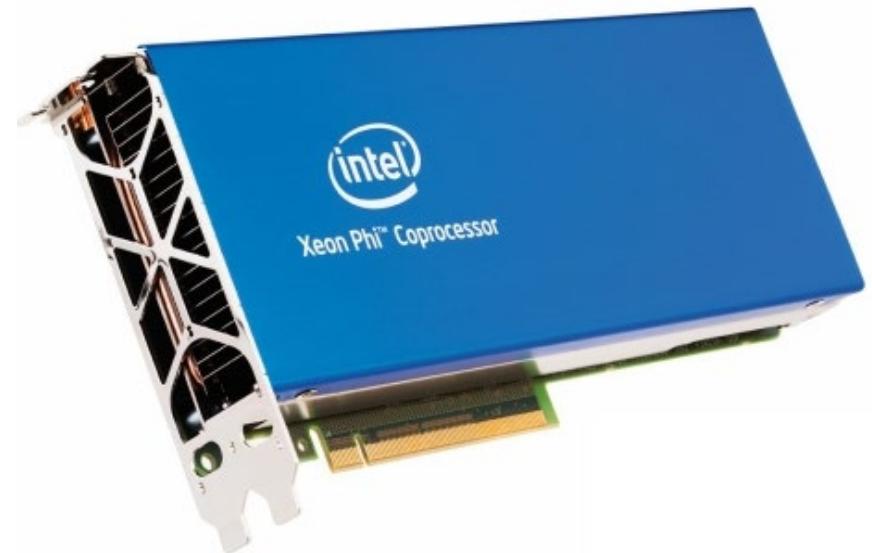
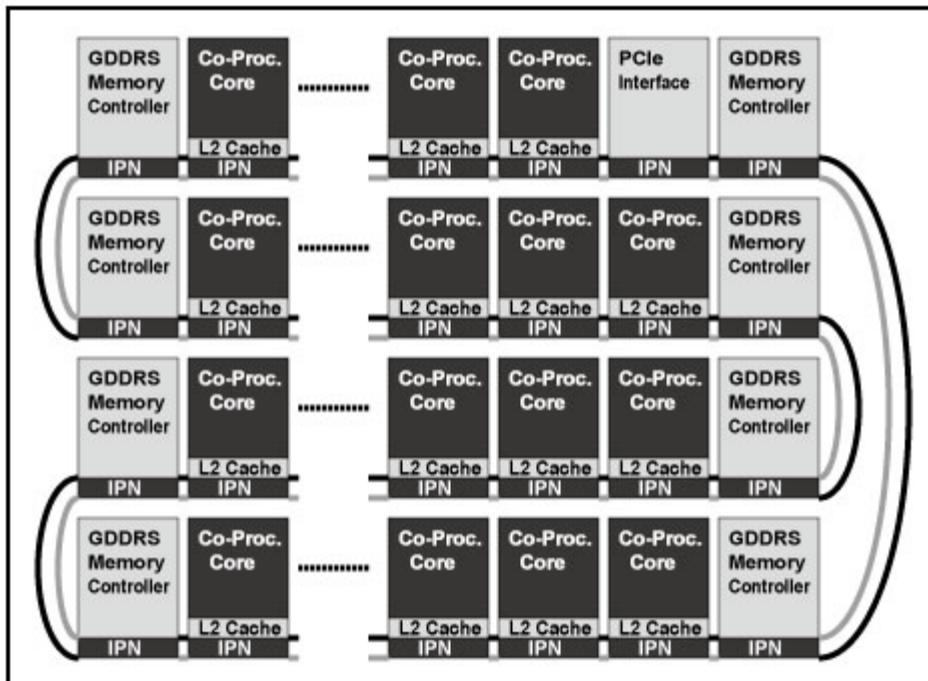


Architecture of NVIDIA GPU



Intel Xeon Phi

- ❑ Intel many-core architecture
- ❑ 60~ cores per chip
- ❑ PCI card as an accelerator
- ❑ compatible with Intel architecture
- ❑ Knights Landing Gen can be used as a stand-alone CPU

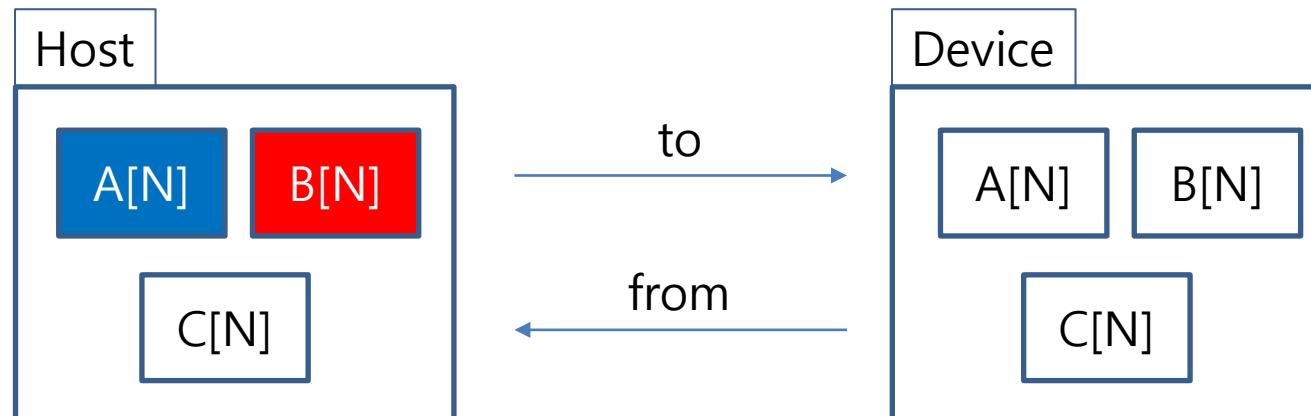


target Directive

- ☐ accelerator has dedicated memory
- ☐ data should be transferred between host and device
- ☐ **map clause**

```
double A[N], B[N], C[N];
```

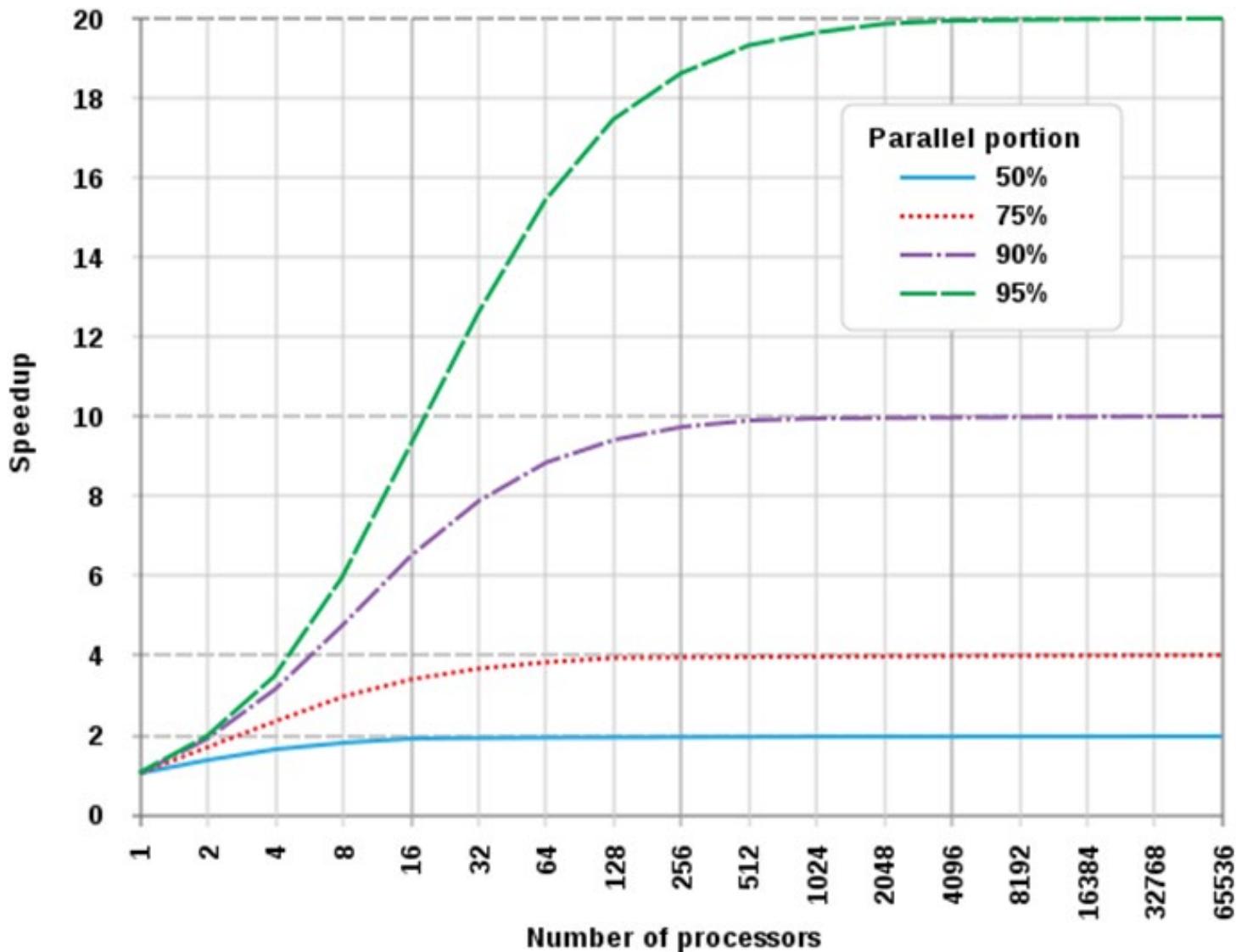
```
#pragma omp target map(to: A[0:N], B[0:N]) map(from: C[0:N])
#pragma omp parallel for
for (int i = 0; i < N; i++) {
    C[i] = A[i] + B[i];
}
```



Parallel Efficiency



Amdahl's Law





**Thanks for listening!
Any questions?**

レポート課題

- 以下のように宣言された行列Aとベクトルxの積yを計算するプログラムを作成すること
 - ※データは必ず任意の値で初期化
 - ※同等のFortranに書き換えても構わない
- 逐次コードの変更はせず、OpenMP指示文の挿入だけで並列化を行うこと

```
#define M 4096  
#define N 4096  
  
double A[M][N], x[N], y[M];
```

- 複数のコア(最低4コア)を持つ計算機環境で性能測定を行い、1,2,4スレッドでの性能(実行時間)をグラフで示すこと