Computers for Lattice Field Theories

Y. Iwasaki [a*]

[a]Institute of Physics, University of Tsukuba, Ibaraki 305, Japan

Parallel computers dedicated to lattice field theories are reviewed with emphasis on the three recent projects, the Teraflops project in the US, the CP-PACS project in Japan and the 0.5-Teraflops project in the US. Some new commercial parallel computers are also discussed. Recent development of semiconductor technologies is briefly surveyed in relation to possible approaches toward Teraflops computers.

1. Introduction

Numerical studies of lattice field theories have developed significantly in parallel with the development of computers during the past decade. Of particular importance in this regard has been the construction of dedicated QCD computers (see Table 1 and for earlier reviews see Ref.[1]) and the move of commercial vendors toward parallel computers in recent years. Due to these developments we now have access to parallel computers which are capable of 5–10 Gflops of sustained speed.

However, a fully convincing numerical solution of many of lattice field theory problems, in particular those of lattice QCD, requires much more speed. In fact typical number of floating point operations required in these problems, such as full QCD hadron mass spectrum calculations, often exceeds 10^{18}, which translates to 115 days of computing time with the sustained speed of 100 Gflops. Under this circumstance we really need computers with a sustained speed exceeding 100 Gflops.

In this talk I review the present status of effort toward construction of dedicated parallel computers with the peak speed of 100–1000 Gflops. Of the six projects in this category (see Table 1), APE100[2] is near completion and ACPMAPS upgraded[3] is running now. Because they have already been reviewed previously[1], we shall only describe their most recent status. The three recent projects, the Teraflops project[4,5] in the United States, the CP-PACS project[6] in Japan and the 0.5-Teraflops[7] project in the United States, are at a varying stage of development. I shall describe them in detail. Finally the APE1000[8] is the future plan of the APE Collaboration, of which details are not yet available.

Table 1
List of dedicated QCD computers

Project	Peak speed Gflops	year
Columbia 16	0.25	1985
64	1.0	87
256	16	89
APE 4	0.25	86
16	1.0	88
QCDPAX	14	90
GF11	11	91
ACPMAPS	5	91
APE100	6($\rightarrow$ 100)	92($\rightarrow$ 94)
ACPMAPS upgraded	50	93
Teraflops	1,600	96
CP-PACS	$\geq$ 300	96
0.5Teraflops	800	95
APE1000	$\sim$ 1000	

A key ingredient in the fast progress of parallel computers in recent years is the development in semiconductor technologies. Understanding this aspect is important when one considers possible approaches toward a Teraflops of speed. I shall therefore start this review with a brief reminder of the development of vector and parallel com-

*Review talk at *Lattice 93*, Dallas, USA.

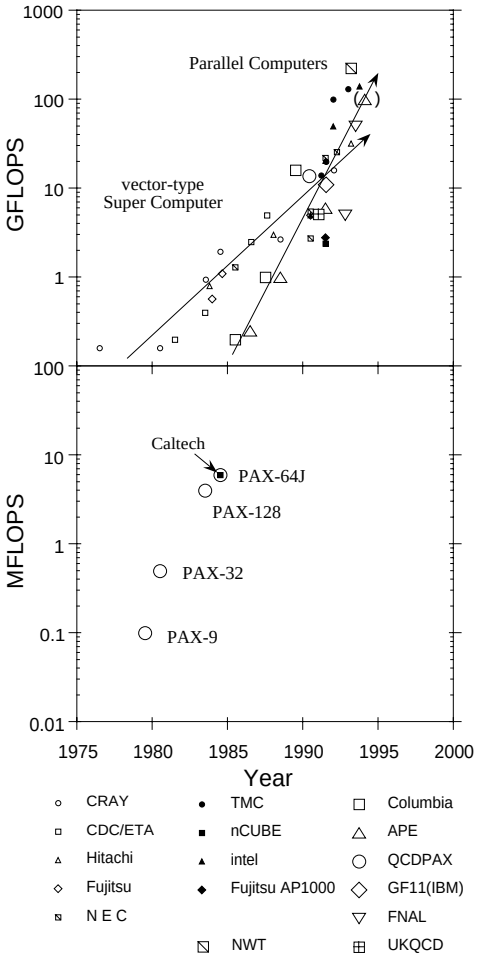

Figure 1. Progress of theoretical peak speed.

puters and the technological reasons why recently parallel computers have exceeded vector computers in the computing capability (Sec. 2). The status of APE100 and ACPMAPS upgraded are summarized in Sec. 3. The US Teraflops, CP-PACS and 0.5-Teraflops projects are described in Sec. 4. Powerful parallel computers are also available from commercial vendors. In Sec. 5 I shall discuss two new computers, the Fujitsu VPP500 and CRAY T3D. After these reviews I discuss several architectural issues for computers toward Teraflops in Sec. 6. A brief conclusion is given in

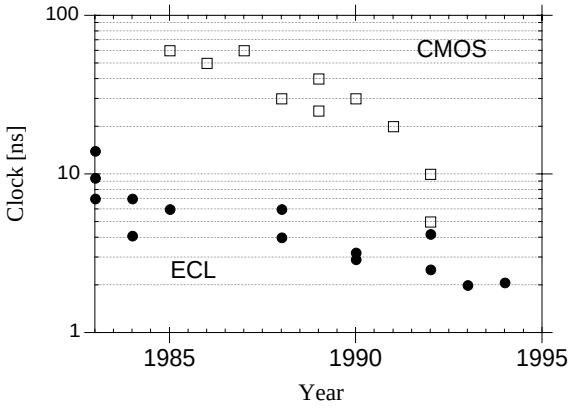

Figure 2. Machine clock of ECL and CMOS semiconductors.

Sec. 7.

2. Recent development of computers and semiconductor technology

In the upper part of Fig. 1 we show the progress of peak speed of vector and parallel computers over the years. Small symbols correspond to the first shipping date of computers made by commercial vendors, with open ones for vector and filled ones for parallel type. Parallel computers dedicated to lattice QCD are plotted by large symbols. We clearly observe that the rate of progress for parallel computers is roughly double that of vector computers and that a crossover in peak speed has taken place from vector to parallel computers around 1991.

The "linear fit" drawn in Fig. 1 for parallel computers can be extrapolated to the period prior to 1985. QCDPAX is the fifth generation computer in the PAX series[9] and there are four earlier computers starting in 1978. In the lower part of Fig. 1 the peak speed of these computers are plotted in units of Mflops together with that of the Caltech computer described, for example, by Norman Christ at Fermilab in 1988[1]. It is amusing to observe that the rapid increase of speed of parallel computers has been continuing for over a decade since the early days.

It is important to note that the first three PAX

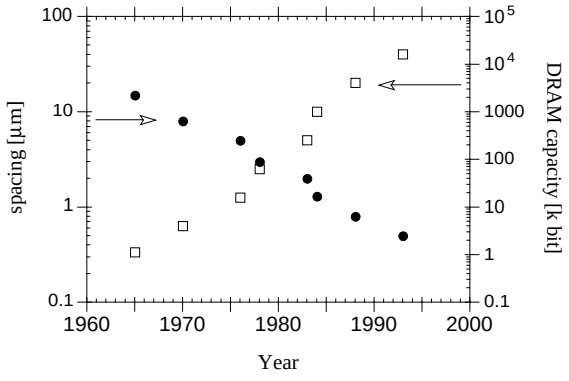

Figure 3. Development of minimum spacing of LSI and capacity of DRAM.

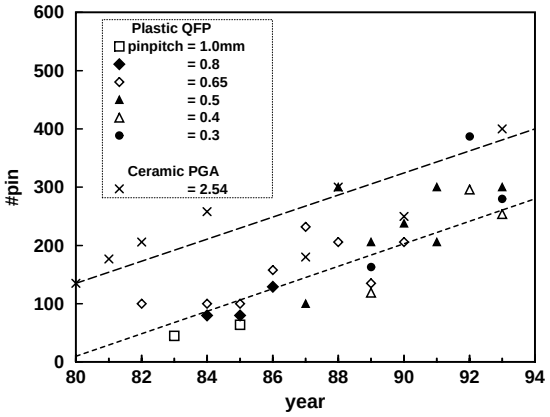

Figure 4. Evolution of the number of pins. (From "Nikkei Electronics" August 2, 1993.)

computers are limited to 8 bit arithmetic and the fourth one to 16 bit. We also recall that the first Columbia computer used 22 bit arithmetic. Thus not only the peak speed but also the precision of floating point numbers has increased significantly for parallel computers. Now the 64 bit arithmetic is becoming standard.

To see more closely why the crossover happened, let us look at the development of technology of semiconductors. In Fig. 2 we show how machine clocks become faster in the case of ECL which is utilized in vector-type supercomputers as well as in the the case of CMOS which is used in personal computers and workstations. As we can see, the speed of CMOS is about 10-fold less than ECL. However, the power consumption and the heat output are much lower than those of ECL. Furthermore the speed of CMOS itself has become comparable to that of ECL of the late 1980's.

The machine cycle of one nano-second is a kind of limit to reach. This is understandable because one nano-second is the time in which light travels 30cm. In this time interval one has to load data from memory to a floating point operation unit, make a calculation and store results to the memory. Even in the ideal case of pipelined operations, one nano-second corresponds only to one Gflops. Usually a vector computer has a multiple operation units which consists of, for example, 8 floating point operation units (FPUs). Because of this, the theoretical peak speed becomes 8 Gflops. Further it has multiple sets of this kind of multiple FPUs; in the case of 4 sets the peak speed becomes 32 Gflops. This is the way how a vector computer gets the peak speed of order of 10 Gflops. That is, recent vector computers are already parallel computers. However, it is rather difficult to proceed further in this approach because of the power consumption and the heat output.

On the other hand, the development of CMOS semiconductor technology, with its small-size, high speed and low power consumption, has made it possible to construct a massively parallel computer which is composed of order of 1,000 nodes with the peak speed which exceeds that of vector-type supercomputers. This is the reason why the crossover occurred.

The speedup of CMOS has become possible due to the development of LSI technology. Figure 3 shows the development in terms of the minimum feature size or minimum spacing. Now the spacing has been reduced to 0.5 micron. This development has also lead to a substantial increase of DRAM bit capacity which has recently reached the level of 16Mbit. The speed of transistors has also increased with the decrease of minimum spacing because electrons can move through the

Table 2
Characteristics of dedicated QCD computers I

Project	Columbia	APE	QCDPAX	GF11	ACPMAPS
peak speed	16 Gflops	1 Gflops	14 Gflops	11 Gflops	5 Gflops
processors	256	16	480	566	256
network	2d torus	linear array	2d torus	Memphis switch	crossbar and hypercube+
arichitecture	MIMD	SIMD	MIMD	SIMD	MIMD
CPU	80286	—	68020	—	Weitek
FPU	80287	Weitek1032×4	LSI Logic	Weitek1032×2	XL8032
	Weitek3364×2	Weitek1033×4	L64133	Weitek1033×2	chip set
SRAM	2MB	—	2MB	64KB	2MB
DRAM	8MB	16MB	4MB	2MB	10MB
speed/ processor	64Mflops	64Mflops	32Mflops	20Mflops	20Mflops
host	VAX11/780	μVAX	Sun 3/260	3090	μVAX

minimum spacing in a shorter time. This is the reason why the machine clock has become faster.

The packaging technique has also developed: Figure 4 shows the development of the number of pins of LSI.

Due to these development, it is now not a dream to construct a 1Tflops computer with 64 bit arithmetic with reasonable size and reasonable power consumption.

3. Past and present of dedicated computers

The computers of the first group in Table 1, the three computers of Columbia[10], two versions of APE[11], QCDPAX[12], GF11[13] and ACPMAPS[14], were constructed some years ago and have been producing physics results. The characteristics of these computers are given in Table 2. These computers are already familiar to lattice community. Therefore I refer to earlier reviews [1] for details and just emphasize that a number of interesting physics results have been produced. This fact shows that there is really benefit in constructing dedicated computers.

The computers of the second group in Table 1, the 6 Gflops version of APE100 and ACPMAPS upgraded, have been recently completed. Both are now producing physics results, some of which have been reported at this conference. I list their characteristics in Table 3.

3.1. APE100

The architecture of APE100[2] is a combination of SIMD and MIMD. The full machine consists of 2048 nodes with a peak speed of 100 Gflops. The network is a 3-dimensional torus. Each node has a custom-designed floating point chip called MAD. The chip contains a 32-bit adder and a multiplier with a 128-word register file. The memory size is 4Mbytes/node with 80 ns access time 1M ×4 DRAM. The bandwidth between MAD and the memory is 50 Mbytes/sec, which corresponds to one word/4 floating point operations. One board consists of $2 \times 2 \times 2 = 8$ nodes with a commuter for data transfer. The communication rates on-node and inter-node are 50 Mbytes/sec and 12.5 Mbytes/sec, respectively. Each board has a controller which takes care of program flow control, address generation and memory control.

The 6 Gflops version of APE 100, which is called TUBE, is running and producing physics results. A TUBE is composed of 128 nodes making a $32 \times 2 \times 2$ torus with periodic boundary conditions. The naming originates from its topological shape. The memory size is 512 Mbytes.

Table 3
Characteristics of dedicated QCD computers II

Project	APE100	ACPMAPS
processors	2048	612
arichi-tecture	SIMD MIMD	MIMD
CPU	MAD (custom)	i860
memory	4MB	32MB
speed/ processor	50 Mflops	80 Mflops
network	3d torus	crossbar hypercube+
host	SUN WS	SGI
peak speed	100 Gflops	50Gflops
arithmetic	32 bit	32 (64) bit

Four TUBEs have been completed.

The sustained speed of a TUBE for the link update is about 1.5 microsecond/link with the Metropolis algorithm with 5 hits. The time for multiplication of the Wilson operator is 0.8 microsecond per site. These rates roughly correspond to 2.5 Gflops to 3 Gflops, which represents 40-50% of the peak speed. These figures show good efficiency.

The physics subjects being studied on TUBE are hadron spectrum and heavy quark physics, the results of which have been reported at this conference.

A Tower which consists of 4 TUBEs with a peak speed of 25 Gflops is being assembled now and should be working in the late fall of 1993. The full machine which is composed of 4 Towers with a peak speed of 100 Gflops is expected to be completed by the first quarter of 1994.

3.2. ACPMAPS Upgraded

This is an upgrade of the ACPMAPS replacing the processor boards without changing the communication backbone[3]. The ACPMAPS is a MIMD machine with distributed memory. On each node there are two Intel i860 microprocessors with a peak speed of 80 Mflops. The memory size is 32 Mbytes of DRAM for each node. The full machine consists of 612 i860 with a peak speed of 50 Gflops and has 20 Gbytes of memory.

The network has a cluster structure: one crate consists of 16 boards with a 16-way crossbar. A board can be either a processor node or a Bus Switch Interface board. The 16-way crossbars are connected in a complicated way which makes a hyper-cube and other extra connections. The throughput between nodes is 20 Mbytes/sec.

ACPMAPS has a strong distributed I/O system: there are 32 Exabyte tape drives and 20 Gbytes of disk space. This mass I/O subsystem is one of characteristics of ACPMAPS.

The software package CANOPY which was well described several times[14,3] is very powerful to distribute physical variables to nodes without knowing the details of the hardware.

The ACPMAPS is running and doing calculations of the quenched hadron spectrum and heavy quark physics, the results of which have been reported at this conference.

The sustained speed measured on a $32^3 \times 48$ lattice are as follows. One link update time by a heat-bath method is 0.64 micro-second per link. One cycle of conjugate gradient inversion of the Wilson operator by red-black method takes about 0.64 micro-second per site. The L inversion together with the U back-inversion in the ILUMR method takes 2.23 micro-second per site. These figures for the sustained speeds are about 10-20% of the peak speed. Therefore efficiency is not so good compared to TUBE. However, there are several good characteristics. First, it supports both 64 and 32 bit arithmetic operations. The network is very flexible and the distributed I/O system is convenient for users.

4. Project under way and proposed

The three projects of the third group in Table 1, the Teraflops project, the CP-PACS project and the 0.5-Teraflops project are well under way. The basic design targets are listed in Table 4.

4.1. Teraflops project

The Teraflops project[4] has changed significantly since last year. The new plan (Multi-

Table 4
Characteristics of dedicated QCD computers III

Project	Teraflops	CP-PACS	0.5Tflops
processors	8K	1–1.5K	16K
arichi-tecture		MIMD	MIMD
CPU		enhanced PA-RISC	DSP TI
memory	32MB	64MB	2MB
speed/ processor	200–300 Mflops	200–300 Mflops	50 Mflops
network		hypercrossbar	4d torus
host		main frame	SUN WS
peak speed	$\geq$ 1.6Tflops	$\geq$300Gflops	0.8Tflops
arithmetic	64bit	64 bit	32 bit

disciplinary Teraflops Project)[5] utilizes Thinking Machine's next generation platform instead of CM5 as originally planned. A floating point processing unit(FPU) called an arithmetic accelerator is to be constructed with a peak speed in the range of $200 - 300$ Mflops. One node consists of 16 such FPUs plus one general processor, with a peak speed of more than 3.2 Gflops and 512 Mbytes of memory.

The full machine consists of 512 nodes with a peak speed of at least 1.6 Tflops with 64 bit arithmetic. The sustained speed is expected to be more than 1 Tflops. A preliminary estimate for the cost of the full machine is $\$20 - 25$M. This project is the collaboration of the QCD Teraflops Collaboration[15], MIT Laboratory for computer science, Lincoln Laboratory and TMC. Funding for the project began in the fall of 1992 with start-up funds provided by MIT. The proposal for the whole project will be submitted to NSF, DOE and ARPA this fall. The tentative schedule is to build a prototype node in 1994, a prototype system in 1995 and have the full system in operation in 1996.

4.2. CP-PACS project

We started the CP-PACS (Computational Physics by Parallel Array Computer Systems) project last year[6]. The CP-PACS collaboration currently consists of 22 members[16], a half of them physicists and the other half computer scientists.

The architecture is MIMD with a 3-dimensional hyper crossbar which will be explained later. The target of the peak speed is currently at least 300 Gflops with 64 bit arithmetic. We are making a proposal for additional funds to increase this peak speed. The memory size is planned to be more than 48 Gbytes.

The processor is based on a Hewlett-Packard PA-RISC processor. This is a super-scalar processor which can perform two operations concurrently. We enhance the processor to support efficient vector calculations. The peak speed of one processor is $200 - 300$ Mflops. The enhancement will be described in detail later. For memory we use synchronous DRAM, pipelined by multi-interleaving banks and a storage controller. The memory bandwidth is one word per one machine cycle.

Now let me explain the vector enhancement of the processor. As is well-known, high performance of usual RISC processors like those of Intel, IBM, HP and DEC heavily depends on the existence of cache. However, when the data size exceeds the cache size, effectiveness of cache de-

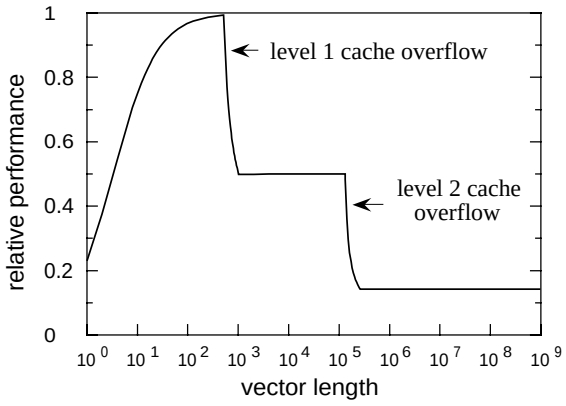

Figure 5. Performance of a RISC processor in a large scale scientific calculation.

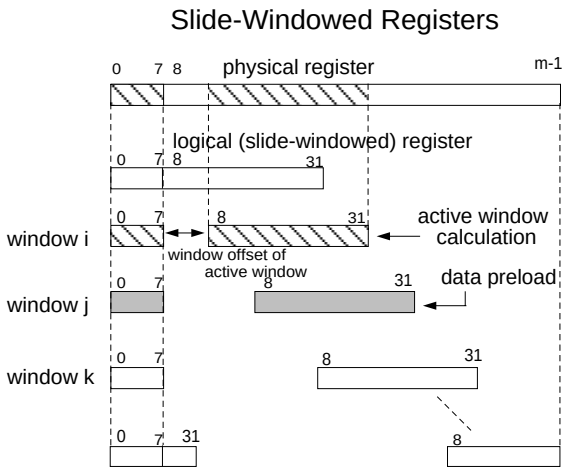

Figure 6. Schematic graph of slide-windowed registers.

creases. Figure 5 shows a typical example of the performance of a RISC processor. When the data size exceeds the size of the on-chip level-1 cache, it drops down by about 50%. Furthermore when it exceeds the size of the level-2 cache, the performance is of order 15% of the theoretical peak speed. This feature is very common to cache-based RISC processors.

To overcome this difficulty, our strategy is to increase the number of floating-point registers without serious changes in the instruction set architecture. This means upward compatibility. However, this is not straightforward because the register fields for instructions are limited; the number of registers is usually limited to 32. To resolve this problem we introduce slide windows as well as preload and poststore instructions[17]. We also pipeline the memory. Because of these features we are able to hide long memory access latency and perform vector calculations efficiently.

Figure 6 is a schematic illustration of how slide windowed registers work. Arithmetic instructions use the registers in the active window which has 32 registers. The preload instruction can load data into registers of the next (or next-to-next) window and the poststore instruction stores data from registers of the previous window. The pitch for the window slide can be chosen by software. Due to the preload and poststore instructions we can use all of m ($m > 32$) physical registers.

Figure 7 is a comparison of the performance with and without slide windows for Livermore Fortran Kernels : <Original> means performance without slide windows, and <Perfect-Cache> represents a hypothetical case for comparison where the cache size is infinite and the data are all in cache. In the case of <Slide-Window>, the number of slide-windowed floating-point registers is assumed to be 64. Except for #14 of Livermore Fortran Kernels, the performance with slide windows is almost equal to that of the perfect cache case and it is about 6 times higher than the original one.

Figure 8 shows the efficiency of performance for the case of multiplication of the Wilson matrix. The dashed line corresponds to efficiency in the case of the code optimized by hand without considering memory bank-conflicts. The solid line is the result of a simulation for the realistic case where the effect of memory bank conflict and the buffer size effect are taken into account. This shows that if the number of registers is larger than 100 the efficiency is more than 75%. We will develop a compiler for the enhanced RISC processor, which will produce optimized codes for the slide-window architecture.

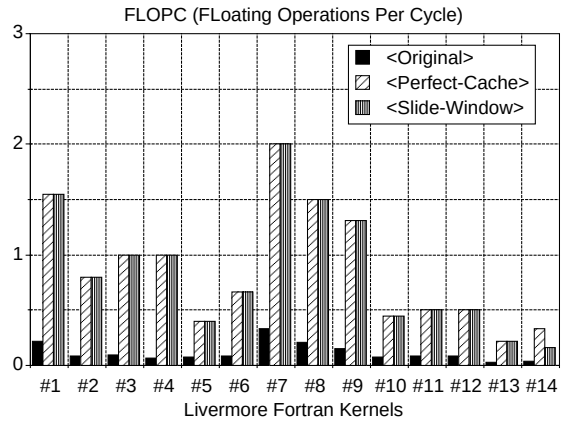

Figure 7. Comparison of performance with and without slide windows for Livermore loops.

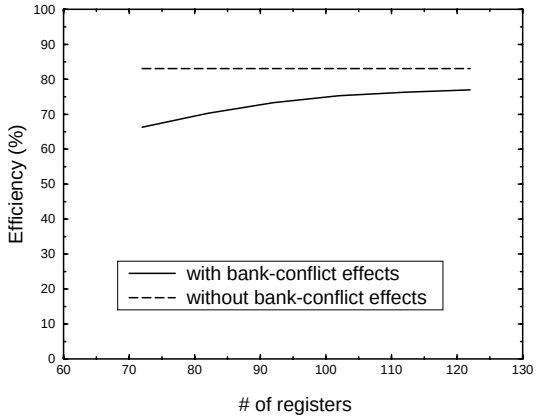

Figure 8. Performance for multiplication of Wilson matrix.

On each processing unit(PU), we place one enhanced PA-RISC processor, local storage(DRAM) and a storage controller(see Fig. 9). NIA stands for Network Interface Adapter and EX for exchanger. On an IO unit(IOU), in addition to the components on PU, we place an IO bus to which disks are connected through IO adapters.

The network is a 3-dimensional hyper crossbar as shown in Fig. 10. It consists of x-direction crossbars as well as y and z direction crossbars. This hyper crossbar network is very flexible: from any node to another node data can be transferred through at most three switches. The data transfer is made by message passing with wormhole routing. The latency is expected to be of order of a few micro-second. A block-strided transfer is supported. We have also a global synchronization in addition to the hyper crossbar network.

The system configuration of the CP-PACS with distributed disks is depicted in Fig. 10. The disk space is more than 500 Gbytes in total. We use RAID5 which has extra parity bits. In general, when the number of disks is large as in this case, the MTBF(mean time between failure) becomes of order of one month. With RAID there is no such problem, however. The number of nodes, not fixed yet, is from 1000 to 1500.

The host is a main frame computer with modifications for massive data transfer between the CP-PACS and the external disk storage.

A prototype with the PA-RISC without enhancement, which will be used mainly for tests of network hardware, will be completed in early 1994 and the full scale machine with the newly developed processor is scheduled to be completed by spring 1996.

The project is being carried out by a collaboration with Hitachi Ltd. A new center called "Center for Computational Physics" was established at University of Tsukuba for the development of CP-PACS. A new building for the center, where the new machine will be installed, was completed in the summer of 1993. The fund for the development of CP-PACS is about $14M.

4.3. 0.5-Teraflops project

This project started quite recently[7]. The project is a collaboration of theoretical physicists and experimental physicists[18]. The machine consists of 16K nodes making a 4-dimensional torus $16 \times 16 \times 16 \times 4$ with a peak speed of 0.8 Tflops with 32 bit arithmetic. It is expected that the sustained speed for QCD is about 0.4 Tflops.

The node architecture is depicted in Fig. 11.

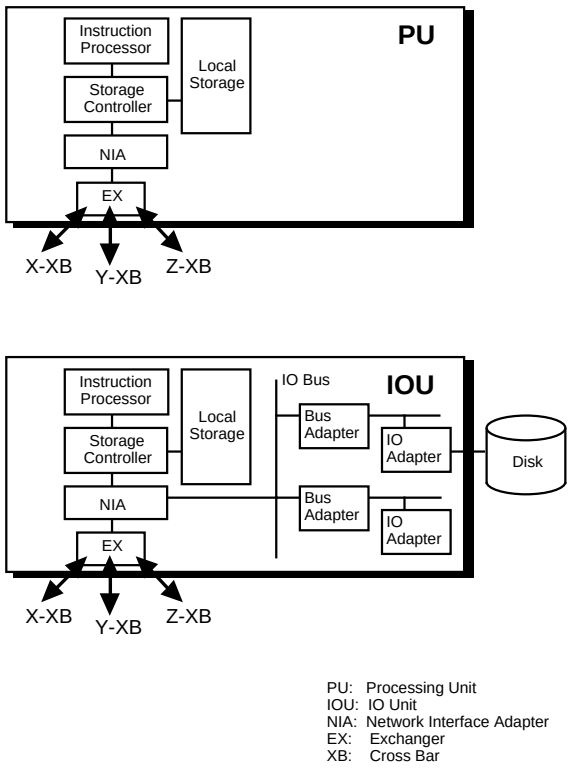

Figure 9. Schematic configuration of Processing Unit(PU) board and IO Unit(IOU) board of CP-PACS.

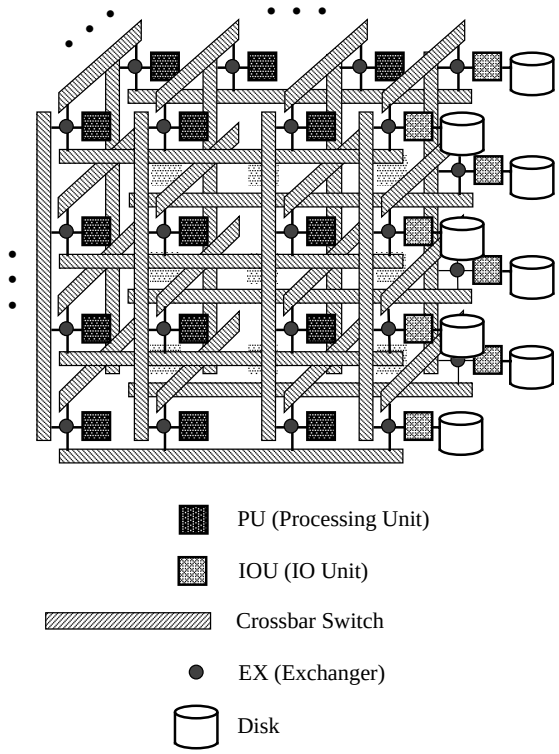

Figure 10. System configuration of CP-PACS.

The processor is DSP(Digital Signal Processor) by Texas Instruments. A 32 bit addition and multiplication can be performed concurrently with 40 ns machine cycle. This leads to 50 Mflops for each node. It executes one word read for one machine cycle and one word write for two machine cycles. The DSP has 2K words of memory on chip. The size is small (3.0 cm^2), the power consumption very low (less than 1 Watt) and the price is less than 50$.

Each node has 2 Mbytes of DRAM. The maximum bandwidth between the processor and the memory is 25 Mwords/sec. The memory size is 32 Gbytes in total.

The node gate array(NGA) which is shown in Fig. 12 is to be newly developed. The design has been partly finished. It plays the roles of memory manager, network switch and specialized cache as a buffer. The buffer size is chosen in such a way that multiplications of 3×3 matrices on 3-vectors can be efficiently done.

The 4-dimensional network is connected by eight bi-directional lines of NGA. Because the data transfer is made by handshaking, the latency is not low. To hide this latency, there is a mode called "store and pass through". In the calculation of the inner-product of two vectors which appears in the conjugate gradient method, the data transfer which takes 70 % of the total time without this mode reduces to 28 % with this mode. It supports a block-strided transfer.

The mechanical design of a mother board is shown in Fig. 13. On the mother board there are $2 \times 2 \times 4 \times 4 = 64$ daughter boards with last 4

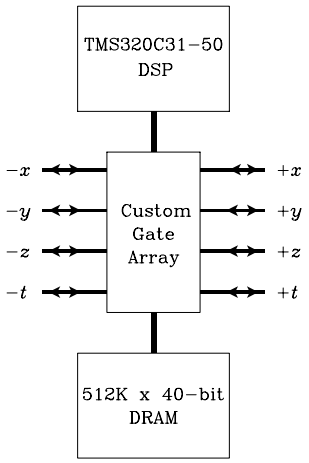

Figure 11. Schematic diagram of one node of the 0.5-Teraflops machine.

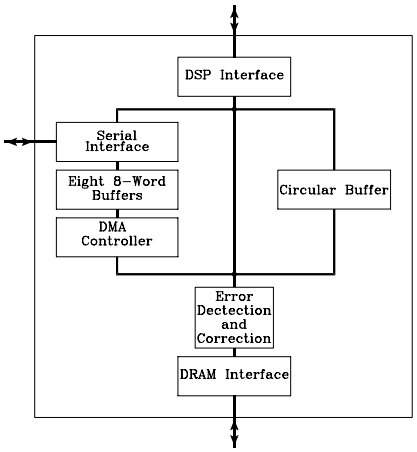

Figure 12. Schematic diagram of NGA(node gate array) for the 0.5-Teraflops machine.

making a loop. Each node has a SCSI port to which peripheral tape and disk drives are connected. One of 256 boards of the full machine is connected to the host. The disk space is 48 Gbytes in total. The data transfer from disk to tape or visa-visa can be done concurrently with physics calculations.

The power consumption is expected to be about 50 KW, which is very low compared with other projects. The test board will be completed by summer 1994 and the full machine by summer 1995. The funds for 128 node machine with a peak speed of 6.4 Gflops is supported by DOE. The proposal for the full machine will be submitted in spring 1994.

4.4. APE1000

This is a successor of APE 100 with a peak speed of 1Tflops with 64 bit arithmetic[8]. The project will start by the end of 1994.

5. Commercial computers

I list the characteristics of the most powerful commercial computers in Table 5 and describe in some details the two new ones below. For other

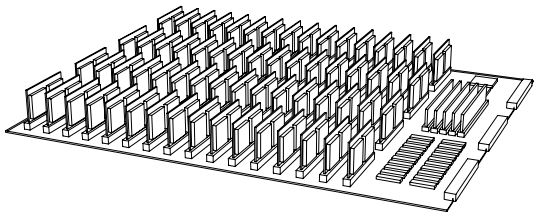

Figure 13. Mechanical design of a mother board of the 0.5-Tflops project.

computers I refer to the earlier reviews[1].

5.1. VPP500

This is the latest machine from Fujitsu. Each node is a vector processor with the same architecture as VP400 with a peak speed of 1.6 Gflops. Because of this, it is called a vector-parallel machine by Fujitsu. One node is a multi-chip-module which consists of 121 LSIs, a part of which is composed of GaAs. Each node has 128 Kbytes of vector registers and 2 Kbytes of mask registers. The memory size is 256Mbytes/node.

Table 5
Characteristics of some commercial computers

Machine	CM-5	T3D	VPP500	Paragon
processors	1024	2048	222	4096
arichi-tecture	SIMD +MIMD	MIMD	MIMD	MIMD
CPU	SPARC +FPU	DEC Alpha	MCM (custom)	i860XP
Memory	32–128MB	16(64)MB	256MB	32MB
speed/ processor	128Mflops	150Mflops	1.6Gflops	75Mflops
network	fat tree	3d torus	crossbar	2d mesh
host	SUN WS	C90	VP2600	CONVEX
peak speed	130 Gflops	300 Gflops	355 Gflops	320 Gflops
data transfer	5-20 MB/sec	300 MB/sec	400 MB/sec	200MB/sec

The network is a complete crossbar connecting all nodes, which is very powerful for any application. The bandwidth for data transfer is 400 Mbytes/sec for each direction. The OS is UNIX and the language is Fortran plus directives for parallel procedures.

The maximum number of nodes is 222 with the peak speed of 355 Gflops. The power consumption is 6KW/node. The power needed for the full machine is more than 1 MW.

A small VPP500 with 4 processors is scheduled to be installed at Aachen this December. Another one with 7 processors will be installed at the Institute of Space and Astronomical Laboratory of Japan next January.

5.2. T3D

This is the machine just announced by CRAY. The node processor is the DEC Alpha chip, which is one of the most powerful RISC chip in the market. The clock cycle is 6.7ns and the peak speed of the chip is 150Mflops. The memory size is 16Mbytes for one node with 4Mbit DRAM at present. It will be upgraded soon to 64Mbytes with 16Mbit DRAM. The memory is globally shared and physically distributed.

The network is a 3-dimensional torus. The bandwidth for data transfer is 300MB/sec for each direction. The latency of the communication is very low, less than 1 microsecond for hardware overhead.

It is a MIMD machine with a maximum peak speed of 300Gflops when it is composed of 2048 nodes: the maximum number of nodes which is 1024 at present will be increased to 2048 soon.

The OS is Mach and the language is Cray Research Adaptive Fortran.

The machine with 32 nodes have been already installed at Pittsburgh Supercomputing Center. It will be upgraded to 512 nodes next spring.

5.3. Sustained speed of commercial parallel computers

The MILC collaboration has been running QCD codes on a number of commercial computers including the nCUBE2, the Intel iPSC/860, the Intel Paragon and the TMC CM5. They have results of benchmarks for the conjugate gradient matrix inversion with staggered quarks on these parallel computers[19]. The performances of the benchmarks are plotted in Figs. 14 and 15, respectively, in terms of Mflops/node and the ratio of the sustained speed to the theoretical peak speed. It should be noted that the benchmarks quoted for the CM5 and the Paragon are preliminary. In particular, the communication speed of the Paragon is expected to improve significantly as the operating system is upgraded.

The nCUBE2 is very stable and has nice software. Because nCUBE2 is slow, it is not suitable

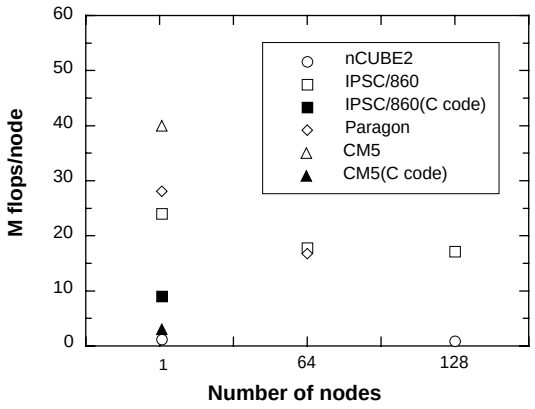

Figure 14. Sustained speed in terms of flops/node of commercial parallel computers for the conjugate gradient matrix inversion with staggered quarks[19]. The results for Paragon and CM5 are preliminary.

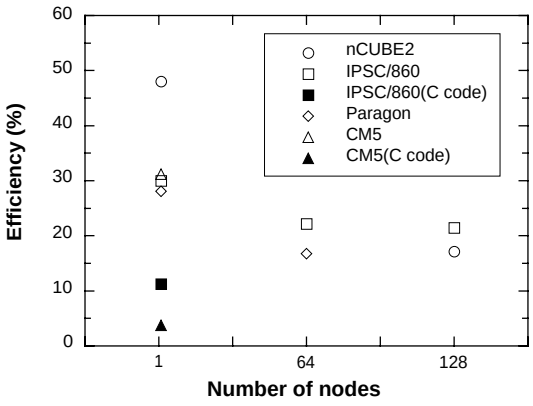

Figure 15. Efficiency in terms of the ratio of the sustained speed to the theoretical peak speed[19].

for large QCD simulations, but it is convenient for software development.

When the code is written in C, the efficiency is very low for iPSC/860 and CM5 as is seen in the figures. Only when they are written in assembly languages, the efficiency becomes around 30%. A similar efficiency has been also reported at this conference by Rajan Gupta[20] for Wilson quarks in the case of CM5.

6. Toward Teraflops computers

6.1. Three strategies

Roughly speaking, there are three strategies to get a 1 Tflops machine as shown in Table 6. The first is a vector-parallel approach taken by VPP500: 2 Gflops $\times$ 500 nodes =1 Tflops. The second is the approach taken by T3D and CP-PACS, that is, to use the most advanced RISC processor with an enhanced mechanism for high throughput between memory and processor: 200-400 Mflops $\times$ 2500-5000 nodes = 1Tflops. The approach taken by the Teraflops project is in between the first and the second in the sense that the peak speed of one FPU is 200–300 Mflops and that of one node is more than 1.6 Gflops. The third approach is to use well-established technology taken by CM5, Paragon, nCUBE and the 0.5-Tflops project: 50-100 Mflops $\times$ 10,000-20,000 nodes = 1 Tflops.

In the first approach, the power consumption and the size will become problematical, although the number of nodes is small. In the second approach, the sustained speed of each node for arithmetic operations and that of the data transfer between nodes will be the key issue. In the third approach the packaging of the whole system and the reliability will be crucial. In spite of these potential obstacles, I believe that the rapid progress of technologies will enable all three approaches

Table 6
Towards 1 Teraflops machines

Speed of CPU Mflops	#CPU	type
2000	500	VPP500 Teraflops
200–400	2,500–5,000	T3D, CP-PACS
50–100	10,000–20,000	0.5Teraflops, CM5, nCUBE, Paragon

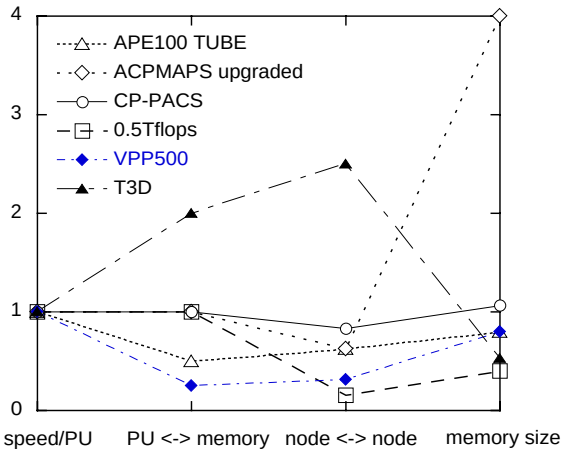

Figure 16. Balance of bandwidth and memory size against processor speed. The normalizations are 1 floating point operation/sec:0.5 words/sec:0.1 words/sec:0.025 words, which is roughly the balance for lattice QCD.

to reach 1 Tflops of theoretical peak speed in a few years. We should note, however, that achieving a high sustained speed with massively parallel computers and having flexibility for applications require additional considerations on the balance of speed of various components and other architectural issues. Let us make brief comments on these points.

6.2. Balance of speed

In Fig. 16 the memory-processor bandwidth, the inter-node communication bandwidth, and the memory size are compared against the processor speed for the computers we reviewed in some detail. The processor speed is normalized to unity, and other normalizations are chosen for the following reason. For QCD calculation it is probably appropriate that the bandwidth between CPU and the memory is one word for two floating point operations. It also will be enough that the bandwidth for inter-node communication is 0.1 words for one floating point operation. For the memory size, the normalization is arbitrary, and I chose 0.025 words of memory size for 1 flops/sec.

We see that each machine has its own characteristic. Securing a high bandwidth between memory and processor and that between nodes, sufficient to keep up with the processor speed, is one of the crucial factor for a high sustained speed. In dedicated computer projects these parameters can be tuned to specific applications (this in fact underlies the cost effectiveness of dedicated computers). For CP-PACS we have chosen the balance in such a way that it is optimized for lattice QCD. We should note, however, that the requirements on the bandwidths in lattice QCD are modest compared to many other applications. Higher bandwidths are probably preferred for general purpose computers as realized in the case of T3D.

There are other points which do not appear in the figure such as the number of floating point registers on each processor, the structure of memory (pipelined or not) and the latency of the communication. These features are also important for the performance of a massively parallel machine. For example, the memory-processor bandwidth relative to the speed of one node is small for VPP500, but it has 8Kbytes of registers which probably compensates it.

6.3. Other issues of architecture

6.3.1. SIMD or MIMD

SIMD is simple and generally sufficient for QCD calculations. However, MIMD is more flexible and can accommodate more varieties of algorithms. An interesting question is whether there are efficient algorithms for inversion of quark matrices which requires a MIMD architecture. Another point is that MIMD hardware is probably simpler than SIMD for a machine with a large number of processors since the clock skew problem will become serious for SIMD.

6.3.2. Topology of network

The 3d torus and 4d torus networks are simple and natural for lattice QCD. However, precision measurement of observables requires finite-size analyses for which we need simulations on a number of lattice sizes. For this point more flexible network is preferable.

6.3.3. 32bit or 64bit

In many cases of lattice QCD calculations it seems that 32bit arithmetic is sufficient. However, for example, at the global reject/accept step of the Hybrid Monte Carlo algorithm on a large lattice, the 32bit precision in not sufficient. In general the 64 bit precision is needed when the algorithm involves global variables.

7. Conclusions

In this review I have surveyed the development of parallel computers and the present status of dedicated computer projects toward Teraflops of speed. In the 1980's parallel computers were in their infancy and TMC was virtually the only company in the field. At that time there was no doubt that constructing dedicated parallel computers by physicists was a beneficial project. In fact dedicated computers which resulted from these projects have produced a number of interesting and important physics results on lattice field theories. The situation has become less clear-cut in recent years due to higher technology needed to achieve faster speed on one part, and emergence of powerful general purpose parallel computers from commercial vendors on the other.

Historically projects for dedicated computers have been carried out by a small group of lattice physicists, in some cases in collaboration with experimental physicists and computer scientists, but without involvement of large commercial companies. The 0.5-Teraflops project follows this spirit. Fully utilizing well-established microprocessor technologies and designing aids which have become commercially available, the project aims to complete a computer precisely tuned to lattice QCD within a short period of time and at a low cost. It is very impressive to learn that this strategy is actually possible for computers approaching a Teraflops of speed. I believe that a vital factor in realizing this approach is the experience gained with the construction of three previous computers at Columbia.

Another possible approach is to depart from the traditional style and to seek for a close collaboration with large companies from the start of the project. This strategy is the one taken by the US Teraflops project and the Japanese CP-PACS project. In the computers planned in these projects the most advanced processors are to be networked together with a large bandwidth. The 0.5-micron semiconductor technology, soon to become that of 0.3 micron, and the packaging technique needed for this type of architecture can not be handled by physicists and computer scientists alone. The cost is necessarily higher and the construction period longer. There are, however, the advantage of choosing more flexible architecture, reliability of hardware, and generally better software environment which is very important for development of application programs and data analysis.

Regardless of the approaches, I think dedicated computer projects still represent an important avenue we should pursue for acquiring the computing power needed for advancement of lattice field theory studies. Hopefully all three computers will be completed in a few years time and produce a variety of fruitful results with some unexpected surprises.

Acknowledgments

I am grateful to many colleagues for useful correspondence and discussions. I would particularly like to thank N. Christ, M. Fischler, F. Karsch, R. Kenway, J. Negele, F. Rapuano, R. Sugar A. Ukawa and D. Weingarten. I am also indebted to the members of the CP-PACS project, in particular K. Nakazawa. Valuable suggestions of A. Ukawa on the manuscript are gratefully acknowledged. Finally I would like to thank K. Kanaya, S. Aoki, H. Nakamura and H. Hirose for the help in the preparation of the manuscript. This work is supported in part by the Grant-in-Aid of the Ministry of Education(No. 05NP0601).

REFERENCES

1. N. Christ, in *Lattice '88*, Nucl. Phys. B(Proc. Suppl.)9 (1989) 549; R. Tripiccione, in *Lattice '89*, Nucl. Phys. B(Proc. Suppl.)17 (1990) 137; N. Christ, in *Lattice '90*, Nucl. Phys. B(Proc. Suppl.)20 (1991) 129; Y. Iwasaki, in

Computing in High Energy Physics '91, Universal Academy Press, Tokyo, (1991)97; D. Weigarten, in *Lattice '91*, Nucl. Phys. B(Proc. Suppl.)26 (1992) 126; E. Marinari, in *Lattice '92*, Nucl. Phys. B(Proc. Suppl.)30 (1993) 122.

2. E. Remiddi, in *Lattice '88*, Nucl. Phys. B(Proc. Suppl.)9 (1989) 562; W. Tross, in *Lattice '90*, Nucl. Phys. B(Proc. Suppl.)20 (1991) 138; F. Rapuano, in *Lattice '91*, Nucl. Phys. B(Proc. Suppl.)26 (1992) 641; C. Battista et al., to be published in International Journal of High Speed Computing; A. Bartoloni et al., Rome preprint 1007, 1008, to be published in International Journal of Modern Physics C.
3. M. Fischler, preprint FERMILAB-TM-1780 (1992).
4. N. Christ, in *Lattice '90*, Nucl. Phys. B(Proc. Suppl.)20 (1991) 129; J. Negele, in *Lattice '92*, Nucl. Phys. B(Proc. Suppl.)30 (1992) 295.
5. J. Negele, private communication.
6. A preliminary report is given in, Y. Oyanagi, in *Lattice '92*, Nucl. Phys. B(Proc. Suppl.)30 (1993) 299.
7. N. Christ, in these proceedings.
8. F. Rapuano, private communication.
9. T. Hoshino, *PAX Computer, High-Speed Parallel Processing and Scientific Computing* (Addison-Wesley, New York, 1989).
10. N. Christ and A. Terrano, IEEE Trans. Comput. 33(1984)344; Y. Deng, in *Lattice Gauge Theory Using Parallel Processors*, ed. X. Li, A. Qiu and H. Ren (Gordon and Breach, New York, 1987), 155; M. Gao,*ibid.*, 369; F. Butler, in *Lattice '88*, Nucl. Phys. B(Proc. Suppl.)9 (1989) 557.
11. E. Marinari, in *Lattice Gauge Field Theory - A Challenge in Large-Scale Computing*, ed.,B. Bunk, K. Mutter and K. Schilling (Plenum Press, New York, 1986); M. Albanese et al., in *Lattice '88*, Nucl. Phys. B(Proc. Suppl.)9 (1989) 562.
12. Y. Iwasaki, T. Hoshino, T. Shirakawa, Y. Oyanagi and T. Kawai, Comp. Phys. Comm. 49(1988) 449; Y. Iwasaki, K. Kanaya, T. Yoshie, T. Hoshino, T. Shirakawa, Y. Oyanagi, S. Ichii and T. Kawai, in *Lattice '89*, Nucl. Phys. B(Proc. Suppl.)17 (1990) 259; Y. Iwasaki, K. Kanaya, T. Yoshie, T. Hoshino, T. Shirakawa, Y. Oyanagi, S. Ichii and T. Kawai, in *Lattice '90*, Nucl. Phys. B(Proc. Suppl.)20 (1991) 141.
13. J. Beetem, M. Denneau and D. Weingarten, in *IEEE Proceedings of the 12th Annual International Symposium on Computer Architecture*, IEEE Computer Society, Washington, D. C.(1985); D. Weingarten, in *Lattice '89*, Nucl. Phys. B(Proc. Suppl.)17 (1990) 272.
14. M. Fischler et al., in *Lattice '88*, Nucl. Phys. B(Proc. Suppl.)9 (1989) 571.
15. The present members of the QCD Teraflops Collaboration are: S. Adler, B. Berg, G. Bhanot, K. Bitar, R. Brower, S. Catterall, C. DeTar, S-J. Dong, T. Draper, P. Dreher, R. Edwards, S. Gottlieb, J. Grandy, H. Hamber, U. Heller, P. Hsieh, S. Huang, A. Kennedy, G. Kilcup, J. Kogut, A. Kronfeld, J-F. Lagae, K-F. Liu, M-P. Lombardo, J. Negele, M. Ogilvie, D. Petcher, J. Potvin, C. Rebbi, R. Renken, S. Sanielevici, Y. Shen, J. Shigemitsu, R. Shrock, E. Shuryak, D. Sinclair, A. Soni, C. Vohwinkel, U-J. Wiese and W. Wilcox.
16. The present members of the CP-PACS project are: S. Aoki, T. Boku, M. Fukugita, T. Hoshino, S. Ichii, M. Imada, Y. Iwasaki, K. Kanaya, H. Kawai, T. Kawai, M. Miyama, M. Mori, H. Nakamura, I. Nakata, K. Nakazawa, M. Okawa, Y. Oyanagi, T. Shirakawa, A. Ukawa, Y. Watase, Y. Yamashita and T. Yoshie.
17. H. Nakamura, H. Imori, K. Nakazawa, T. Boku, I. Nakata, Y. Yamashita, H. Wada and Y. Inagami, in *Proceedings of ACM International Conference on Supercomputing*, Tokyo, (1993) 298.
18. The present members of the 0.5-Teraflops project are: I. Arsenin, D. Chen, N. Christ, R. Edwards, A. Gara, S. Hansen, A. Kennedy, R. Mawhinney, J. Parsons and J. Sexton.
19. R. Sugar, private communication.
20. R. Gupta, in these proceedings.